

Stream Arrows and Stream Lenses

Co-iterative Semantics of Dataflow in Haskell

M. Mendler

University of Bamberg

Introduction

Haskell Recursive Streams

```
Str :: * → *
data Str a = !a :< Str a -- bang pattern (!) for strictness
```

The stream **constructor** `:<` (“grumpy”) induces **destructors** (`s_head`, `s_tail`) and **pattern matching** (case `e1 of !a :< as → e2`).

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Using **recursion** we can generate stream functions:

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s_nats :: Str Int
s_nats = ns where
  ns = 0 :< s_inc ns -- produces 1 grumpy up front
  s_inc (n :< ns) = (n + 1) :< s_inc ns
    -- consumes and produces 1 grumpy
```

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```

With **lazy evaluation** we can access any finite portion of a stream:

```
*> s_print 6 s_nats  ==> <0:1:2:3:4:5:..>
```

Raw Streams are too Shallow

The interaction of **stream functions** coded in this **shallow** way

- ... has **difficult-to-predict grumpy production and consumption behaviour (deadlock and memory leaks)**
- ... is scheduled by the Haskell lazy run-time, with **little user control** on sharing and buffering
- ... does not support **destructive memory update, concurrency or IO interactions.**

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How can we make stream functions **manage their own memory**, permit **IO interaction** and be **schedulable by the application itself?**

Idea: Replace the function type **Str a → Str b** by an abstract type

KP a b ("Kahn Process")

that schedules the sending and waiting for grumpies in **clocked computation cycles** to synchronise with memory and IO.

Kahn Processes as Stream Reactive State Machines

Stream Reactive State Machines

Recall the **co-iterative semantics** of **synchronous** data flow (Caspi, Pouzet)

```
data SNode s a b = SNode s (s → a → (b, s))
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Stream reactive machines for **asynchronous** data flow enrich SNode:

```
data SRM m a b = forall s. Applicative m ⇒  
SRM s (s → [a] → ([a], [b], m s))
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- reaction **returns unconsumed input** values [a]

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- abstract (hidden) state type **s**
- interaction via **input and output lists** **[a]** and **[b]**
- reaction **returns unconsumed input** values **[a]**
- add **state context** **m : * → *** for control continuation, memory, IO.

Kahn Processes

Kahn processes are instances of SRM

```
type KP a b = SRM Df a b
```

```
data Df a = Pause a -- for data flow the identity context  
-- for more continuation control ...| Terminate | Exit |...
```

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```
class Applicative m where  
  pure  :: a → m a  
  (<*>) :: m (a → b) → m a → m b
```

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```

Other Instances

```
type IOF a b = SRM IO a b -- for output and interaction
```

```
type PSF a b = SRM PSM a b -- policy-synchronised memory
```

(Haskell PSM presented at Synchron 2019)

Input-less KP = Scheduled Streams

In and Out of KP

```
schStr2SRM :: Str a → Str Int → KP () a
r_val :: KP () a → Str a    -- total value stream
r_clk :: KP () a → Str Int -- max response at each step
```

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```

Example: Scheduled Stream of Nats

```

r_nats_c :: KP () Int
r_nats_c = schStr2SRM (iter 0 (+1)) (iter 3 (+0))

*> r_print 5 $ r_nats_c
    => <[0,1,2]:[3,4,5]:[6,7,8]:[9,10,11]:[12,13,14]:...>

*> s_print 7 $ r_val r_nats_c => <0:1:2:3:4:5:6:...>
*> s_print 7 $ r_clk r_nats_c => <3:3:3:3:3:3:3:...>

```

Arrow Wiring with Feedback Loops

KP is **not monadic** (Kleisli arrow) but has the structure of general **arrows** ...

```
r_pure  :: (c → b) → KP c b
(≫>)    :: KP b c → KP c d → KP b d
r_first :: KP a b → KP (P a c) (P b c)
(&&&)    :: KP a b → KP a c → K a (P b c)
r_loop   :: KP (P a c) (P b c) → KP a b
```

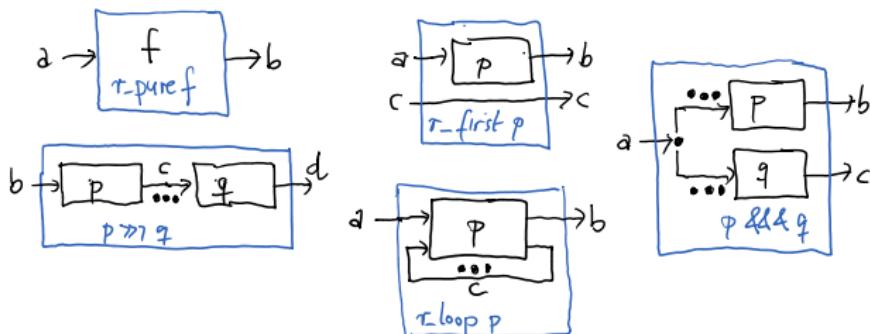
... where P is a pairing that **commutes with lists** (normal tuples do not work)

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This (slightly) generalises:

- J. Hughes: Programming with Arrows. *Sc. of Comp. Progr.* 2000
- R. Paterson: Arrows and Computation. ICFP'2001
- Hudak, Courtney, Nilsson, Peterson: Arrows, Robots and Functional Reactive Programming. AFP'2002

... related to **Freyd** and **trace monoidal categories** (Joyal, Street, Verity).

Extensionality

- Arrow contexts in general are not functionally extensional. There is no “hom-set” equivalence

$$\text{Arrow } a \ b \not\cong \text{Arrow } () \ a \rightarrow \text{Arrow } () \ b.$$

Internal and external function spaces must be distinguished.

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- This applies also to the standard co-iterative semantics:

$$\text{SNode } a \ b \not\cong \text{SNode } () \ a \rightarrow \text{SNode } () \ b \cong \text{Str } a \rightarrow \text{Str } b.$$

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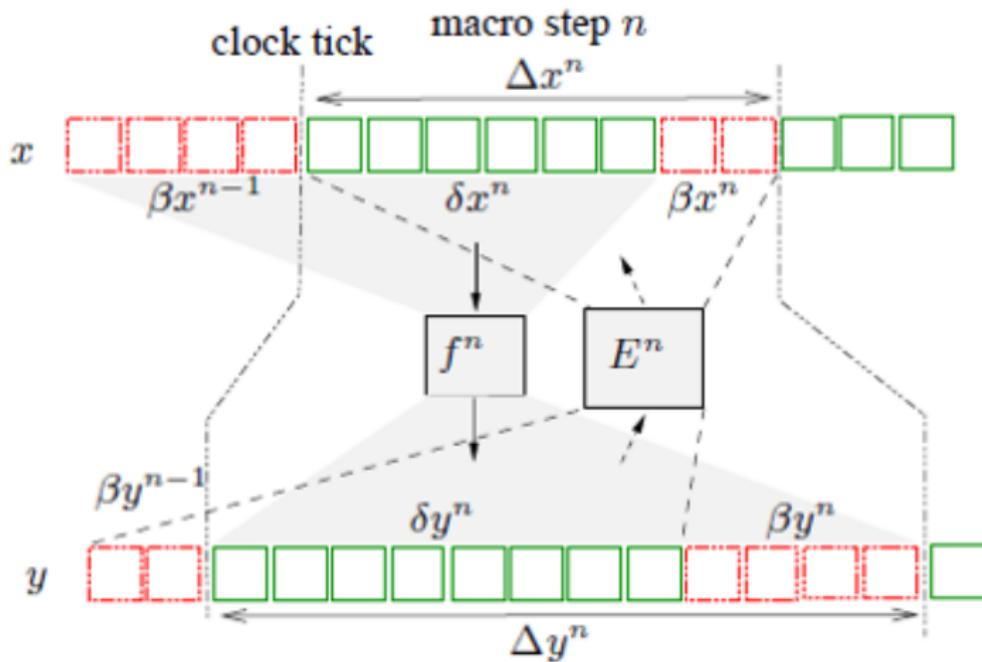
- For **Kahn Processes** the equivalence makes sense:

$$\text{KP } a \ b \cong \text{Str } a \rightarrow \text{Str } b$$

A continuous $f :: \text{Str } a \rightarrow \text{Str } b$ corresponds to a “**differential**¹ **reactive machine** $\Delta f :: \text{KP } a \ b$.

¹see work by Guatto, Tasson, Vienot

Differential Interaction with Environment



Kahn Processes & Control Flow

ArrowPlus Structure

Data Flow: The arrow structure plus primitive building blocks

```
r_fby_n :: a → KP a a          -- initialised delay
r_merge :: KP (P Bool (P a a)) a -- up-sampling
r_when  :: KP (P a Bool) a       -- down-sampling
```

obtains standard (e.g. Lucid Synchron) **data-flow programming**.

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Control Flow Operators: KP arrows can also be programmed in Kahn-McQueen **control-flow** style:

```
r_out    :: b → KP a b → KP a b   -- sending a value
r_in     :: (a → KP a b) → KP a b -- receiving a value
r_pause  :: KP a b → KP a b       -- pausing
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r_out    :: b → KP a b → KP a b   -- sending a value
r_in     :: (a → KP a b) → KP a b -- receiving a value
r_pause  :: KP a b → KP a b       -- pausing

r_srec :: (KP a b → KP a b) → KP a b
r_srec f = p where p = f p        -- state recursion
```

Examples - Output only

We explicitly schedule the value production in bursts:

```
r_halt :: KP a b
r_halt = r_srec r_pause          -- halting

*> r_print 6 r_halt ==> <[] : [] : [] : [] : [] : [] : ...>
```

Examples - Output only

We explicitly schedule the value production in bursts:

```
r_halt :: KP a b  
r_halt = r_srec r_pause -- halting
```

```
*> r_print 6 r_halt ==> <[] : [] : [] : [] : [] : [] : ...>
```

```
ex_4711_1 :: KP a Int  
ex_4711_1 =  
  r_pause $ r_out 4 $ r_out 7 $ r_pause $  
  r_out 1 $ r_pause $ r_pause $ r_out 1 $ r_halt
```

```
*> r_print 6 ex_4711_1 ==> <[], [4,7], [1], [], [1], [], ...>
```

Examples - Input and Output

Synchronous Delay: In each cycle 2 values passed forward

```
r_del_2x2 :: KP Int Int
r_del_2x2 = r_srec $ λend →
  r_in $ λx →                  -- read first value x
  r_in $ λy →                  -- read second y
  r_out x $ r_out y $          -- write first and second
  r_pause $ end                 -- pause and repeat
```

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Synchronous Delay: In each cycle 2 values passed forward

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    r_out x $ r_out y $          -- write first and second
    r_pause $ end                -- pause and repeat
```

Asynchronous Wire: pass forward instantaneously

```
r_del_inst :: KP Int Int
r_del_inst = r_srec $ λend →
    r_in $ λx →                  -- read value
    r_out x $ end                -- write value, repeat w/o pause
```

Examples

The regularly clocked stream of nats...

```
r_nats_c :: KP () Int  
*> r_print 4 $ r_nats_c  
==> <[0,1,2] : [3,4,5] : [6,7,8] : [9,10,11] : ...>
```

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The regularly clocked stream of nats...

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*> r_print 4 $ r_nats_c  
==> <[0,1,2] : [3,4,5] : [6,7,8] : [9,10,11] : ...>
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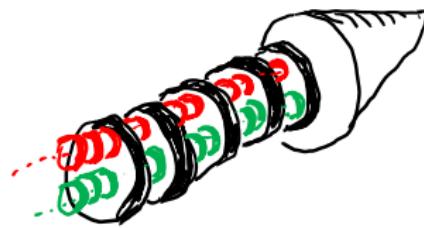
... is passed through `r_del_2x2` and `r_del_inst` with different speed

```
*> i_print 5 $ r_nats_c ≫> r_del_2x2  
==> <[0,1](1) : [2,3](2) : [4,5](3) : [6,7](4) : [8,9](5) : ...>
```

```
*> i_print 4 $ r_nats_c ≫> r_del_inst  
==> <[0,1,2](0) : [3,4,5](0) : [6,7,8](0) : [9,10,11](0) : ...>
```

Note: values (n) in brackets = buffer size

Stream Lenses: Unifying Data & Control Flow



Communication Ports in Stream Contexts

A residual lens² RLens $a \ b \ c$ implements an isomorphism of types $a \cong (b, c)$. It splits a into disjoint pieces b and c from which a can be recombined.

²<https://github.com/ekmett/lens/wiki>

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Horizontal Decomposition of Streams

```
type HPort a b c = ([a] → ([b], [c]), [b] → [c] → [a])  
implements a horizontal (data-flow) cut [a] ≅ ([b], [c])
```

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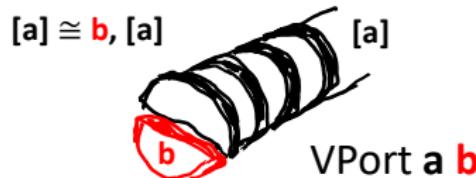
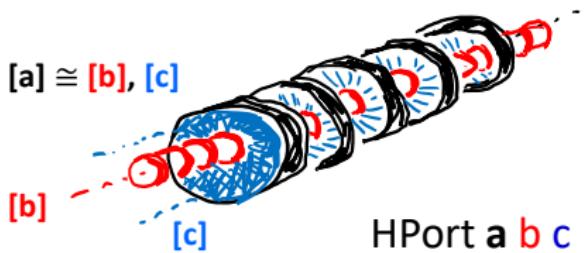
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implements a horizontal (data-flow) cut [a] ≅ ([b], [c])
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Vertical Decomposition of Streams

```
type VPort a b =  
  ([a] → (Maybe b, [a])), Maybe b → [a] → [a])  
implements a vertical (state) cut [a] ≅ (b, [a]).
```

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Residual Stream Lenses



Residual Stream Lenses

Port Access Combinators (selected)

```
hFlow :: HPort a a () -- take full flow
```

```
hGoUp :: HPort a c b → HPort (P a d) c (P b d) -- go up
```

```
hGoDn :: HPort a c b → HPort (P d a) c (P d b) -- go down
```

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```
vState :: VPort a a -- head slice (state) of flow
```

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```

Examples

```
hUp :: HPort (P a c) a c
hUp = hGoUp hFlow          -- pick upper flow

vDn :: VPort (P a c) c
vDn = vGoDn vState        -- head state of lower flow
```

Action Arrows through Lenses

Axiom

```
r_pure :: (a → b) → KP a b
```

Left Cell Introduction (r_first)

```
r_ext :: HPort a b c → KP b d → KP a d
```

Right Cell Introduction (&&&)

```
r_prod :: HPort d a b → KP c a → KP c b → KP c d
```

Feedback (r_loop)

```
r_rec :: HPort a c b → KP a c → KP b c
```

Asynchronous Input and Output

```
r_send :: VPort a c → c → KP d a → KP d a
```

```
r_wait :: VPort a c → (c → KP a d) → KP a d
```

Action Arrows through Lenses

Write $p : a \rightsquigarrow b$ for $p :: \text{KP } a \ b$.

$$\frac{}{r_id : a \rightsquigarrow a} \quad \frac{p : b \rightsquigarrow d \quad \text{var} : [a] \cong [b], [c]}{r_ext \ \text{var}\ p : a \rightsquigarrow d}$$

$$\frac{p : b \rightsquigarrow c \quad q : c \rightsquigarrow d}{p \ggg q : b \rightsquigarrow d} \quad \frac{p : a \rightsquigarrow c \quad \text{split} : [a] \cong [c], [b]}{r_rec\ \text{split}\ p : b \rightsquigarrow c}$$

$$\frac{p : c \rightsquigarrow a \quad q : c \rightsquigarrow b \quad \text{split} : [d] \cong [a], [b]}{r_prod\ \text{split}\ pq : c \rightsquigarrow d}$$

$$\frac{p : d \rightsquigarrow a \quad \text{var} : [a] \cong c, [a]}{r_send\ \text{var}\ v\ p : d \rightsquigarrow a} \quad \frac{x : c \vdash p : a \rightsquigarrow d \quad \text{var} : [a] \cong c, [a]}{r_wait\ \text{var}\ \lambda x. p : a \rightsquigarrow d}$$

Mergesort Example

(suggested by Marc Pouzet)

Mergesort of Streams

```
let node sort x y = c where
  rec xm = current (1 fby c) x
  and ym = current (1 fby (not c)) y
  and clock c = xm ≤ ym
```

α	1	0	0	0	0	1	1	1	1	0	0
$\alpha_1 = 1 \cdot \alpha$	1	1	0	0	0	0	1	1	1	1	0
x	0	1	*	*	*	*	2	3	4	5	*
$xms = \text{current } \alpha_1 xs$	0	1	1	1	1	1	2	3	4	5	5
$\alpha_2 = 1 \cdot \text{not } \alpha$	1	0	1	1	1	1	0	0	0	0	1
y	0	*	0	0	0	4	*	*	*	*	4
$yms = \text{current } \alpha_2 ys$	0	0	0	0	0	4	4	4	4	4	4
$xm \leq ym$	1	0	0	0	0	1	1	1	1	0	1
Dir	B	L	R	R	R	R	L	L	L	L	R

Mergesort of Streams

```
data Dir = L | R | B deriving Show
```

Mergesort of Streams

```
data Dir = L | R | B deriving Show

1 -- wait on first stream for a value greater than threshold
2 -- readx :: Int → KP (P Int Int) Dir
3 readx y =
4   r_wait vUp $ λx →
5   r_send vState L $                      -- signal ‘Left’
6   if x ≤ y then r_pause $ readx y -- repeat
7   else r_pause $ ready x
```

Mergesort of Streams

```
data Dir = L | R | B deriving Show

1 -- wait on first stream for a value greater than threshold
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5   r_send vState L $                      -- signal ‘Left’
6   if x ≤ y then r_pause $ readx y -- repeat
7   else r_pause $ ready x

1 -- wait on second stream for a value greater than threshold
2 -- ready :: Int → KP (P Int Int) Dir
3 ready x =
4   r_wait vDn $ λy →
5   r_send vState R $                      -- signal ‘Right’
6   if y ≤ x then r_pause $ ready x -- repeat
7   else r_pause $ readx y
```

Mergesort of Streams

```
1 -- 'mergesort' two streams
2 -- sort :: KP (P Int Int) Dir
3 sort =
4   r_wait vUp $ λx →      -- read first stream
5   r_wait vDn $ λy →      -- read second
6   r_send vState B $       -- signal 'Both'
7   if x ≤ y then
8     r_pause $ readx y    -- read 'Left' until larger
9   else r_pause $ ready x -- read 'Right' until larger
```

Mergesort of Streams

Unsynchronised Input Streams

```
lVal, rVal :: Str Int
```

```
*> s_print 10 $ lVal  ==> <0:1:2:3:4:5:6:7:8:9:...>
*> s_print 10 $ rVal  ==> <0:0:0:0:4:4:4:4:8:8:...>
```

Mergesort of Streams

Unsynchronised Input Streams

```
lVal, rVal :: Str Int
```

```
*> s_print 10 $ lVal  ==> <0:1:2:3:4:5:6:7:8:9:...>
*> s_print 10 $ rVal  ==> <0:0:0:0:4:4:4:4:8:8:...>
```

Base Clock

```
baseClk :: Str Int
```

```
*> s_print 10 $ baseClk  ==> <1:1:1:1:1:1:1:1:1:1:...>
```

Mergesort of Streams

Unsynchronised Input Streams

```
lVal, rVal :: Str Int
```

```
*> s_print 10 $ lVal  ==> <0:1:2:3:4:5:6:7:8:9:...>
*> s_print 10 $ rVal  ==> <0:0:0:0:4:4:4:4:8:8:...>
```

Base Clock

```
baseClk :: Str Int
```

```
*> s_print 10 $ baseClk  ==> <1:1:1:1:1:1:1:1:1:1:...>
```

Input Streams Synchronised at Base Clock

```
lBStr = schStr2SRM lVal baseClk
rBStr = schStr2SRM rVal baseClk
```

Mergesort of Streams

Input Streams Synchronised at Base Clock

```
*> r_print 10 $ lBStr  
=> <[0] : [1] : [2] : [3] : [4] : [5] : [6] : [7] : [8] : [9] : ...>  
*> r_print 10 $ rBStr  
=> <[0] : [0] : [0] : [0] : [4] : [4] : [4] : [4] : [8] : [8] : ...>
```

Mergesort of Streams

Input Streams Synchronised at Base Clock

```
*> r_print 10 $ lBStr  
=> <[0] : [1] : [2] : [3] : [4] : [5] : [6] : [7] : [8] : [9] : ...>  
*> r_print 10 $ rBStr  
=> <[0] : [0] : [0] : [0] : [4] : [4] : [4] : [4] : [8] : [8] : ...>
```

lBStr and rBStr get merged with a **rythm depending on the streams' values** (needs internal buffering)

```
*> r_print 10 $ (lBStr &&& rBStr) >>> sort  
=> <[B] : [L] : [R] : [R] : [R] : [L] : [L] : [L] : [L] : ...>  
*> i_print 10 $ (lBStr &&& rBStr) >>> sort  
=> <[B] (0) : [L] (1) : [R] (1) : [R] (2) : [R] (3) : [R] (4) : [L] (4) : [L] (4) : [L]
```

Mergesort of Streams

Input Streams Synchronised at Base Clock

```
*> r_print 10 $ lBStr
=> <[0] : [1] : [2] : [3] : [4] : [5] : [6] : [7] : [8] : [9] : ...>
*> r_print 10 $ rBStr
=> <[0] : [0] : [0] : [0] : [4] : [4] : [4] : [4] : [8] : [8] : ...>
```

lBStr and rBStr get merged with a **rythm depending on the streams' values** (needs internal buffering)

```
*> r_print 10 $ (lBStr &&& rBStr) >> sort
=> <[B] : [L] : [R] : [R] : [R] : [L] : [L] : [L] : [L] : ...>
*> i_print 10 $ (lBStr &&& rBStr) >> sort
=> <[B] (0) : [L] (1) : [R] (1) : [R] (2) : [R] (3) : [R] (4) : [L] (4) : [L] (4) : [L] (4) : ...>
```

Input Consumption Rates

```
*> s_print 10 $ lClk => <1:1:0:0:0:0:1:1:1:1:...>
*> s_print 10 $ rClk => <1:0:1:1:1:1:0:0:0:0:...>
```

Mergesort of Streams

The value streams **synchronised** according to their consumption rates:

```
-- lClk, rClk :: Str#(Int)
lCStr, rCStr :: RFArrow#(m, rsm) rsm(m) Int
lCStr = schStr2SRM(lVal, lClk)
rCStr = schStr2SRM(rVal, rClk)

*> r_print(10, lCStr)
=> <[0]:[1]:[]:[[]:[[]:[[]:[2]:[3]:[4]:[5]:...]>
*> r_print(13, rCStr)
=> <[0]:[]:[0]:[0]:[0]:[4]:[]:[[]:[[]:[4]:[4]:[4]:[4]:...]>
```

Mergesort of Streams

The value streams **synchronised** according to their consumption rates:

```
-- lCStr, rCStr :: Str Int
lCStr, rCStr :: RFArrow m rsm => rsm m () Int
lCStr = schStr2SRM lVal lCStr
rCStr = schStr2SRM rVal rCStr

*> r_print 10 $ lCStr
=> <[0] : [1] : [] : [] : [] : [2] : [3] : [4] : [5] : ...>
*> r_print 13 $ rCStr
=> <[0] : [] : [0] : [0] : [0] : [4] : [] : [] : [] : [4] : [4] : [4] : ...>
```

Now we can operate **without buffering**

```
*> r_print 13 $ (lCStr &&& rCStr) >>> sort
=> <[B] : [L] : [R] : [R] : [R] : [L] : [L] : [L] : [R] : [R] : [R] : ...>
*> i_print 13 $ (lCStr &&& rCStr) >>> sort
=> <[B] (0) : [L] (0) : [R] (0) : [R] (0) : [R] (0) : [R] (0) : [L] (0) : [L] (0) : [L]
```

Clock Typing of Mergesort?

If `sort :: KP (P Int Int) Dir` corresponds to a stream function
`sort :: Str Int → Str Int → Str Dir`,
then what is its clock type?

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- We extend clock type schemes σ by event types $\Sigma \alpha. \sigma$ and class constraints $C \Rightarrow \sigma$.

Clock Typing of Mergesort?

If $\text{sort} :: \text{KP}(\text{P Int Int}) \text{ Dir}$ corresponds to a stream function
 $\text{sort} :: \text{Str Int} \rightarrow \text{Str Int} \rightarrow \text{Str Dir}$,
then what is its clock type?

- We extend clock type schemes σ by event types $\Sigma \alpha. \sigma$ and class constraints $C \Rightarrow \sigma$.

$$\text{sort} : \forall \alpha. \forall \alpha_1. \forall \alpha_2. \alpha_1 \rightarrow \alpha_2 \rightarrow \Sigma \alpha_3. C \Rightarrow \underline{1}$$

$$C =_{\text{df}} \alpha_1 = \alpha \circ (1 \cdot \alpha_3) \wedge (\alpha_2 = \alpha \circ (1 \cdot \text{not } \alpha_3)).$$

Conclusion

Summary

- Lazy lists [a] as finite approximations of $\text{Str } a$ to generate a schedulable encoding of $\text{Str } a \rightarrow \text{Str } b$ as an arrow $\text{KP } a \ b$ (Haskell is algebraically compact)
- Stream lenses for uniform data and control flow programming.

Conclusion

Summary

- Lazy lists [a] as finite approximations of $\text{Str } a$ to generate a schedulable encoding of $\text{Str } a \rightarrow \text{Str } b$ as an arrow $\text{KP } a \ b$ (Haskell is algebraically compact)
- Stream lenses for uniform data and control flow programming.

Questions

- Are clocks properties of streams or properties of arrows?
- What is the clock of a multi-input, multi-output KP process?
- Can we give a clock type system that directly types the control flow primitives?

Stopwatch (simplified)

Synchronous Read and Write

Input ? and output ! act on the first stream value of the interface cell. We assume that **only one value** is consumed and produced **per cycle**.

```
(?) :: VPort a c → (c → KP a d) → KP a d
(!) :: VPort a c → c → KP d a → KP d a
```

Demo

```
chrono :: KP Event Double
chrono = stopm 0                                -- the controller

flToDig :: KP Double Graphic
flToDig = r_lift1_n floatToDigits   -- the rendering

chronogr :: KP Event Graphic
chronogr = chrono ≫ flToDig           -- assembly

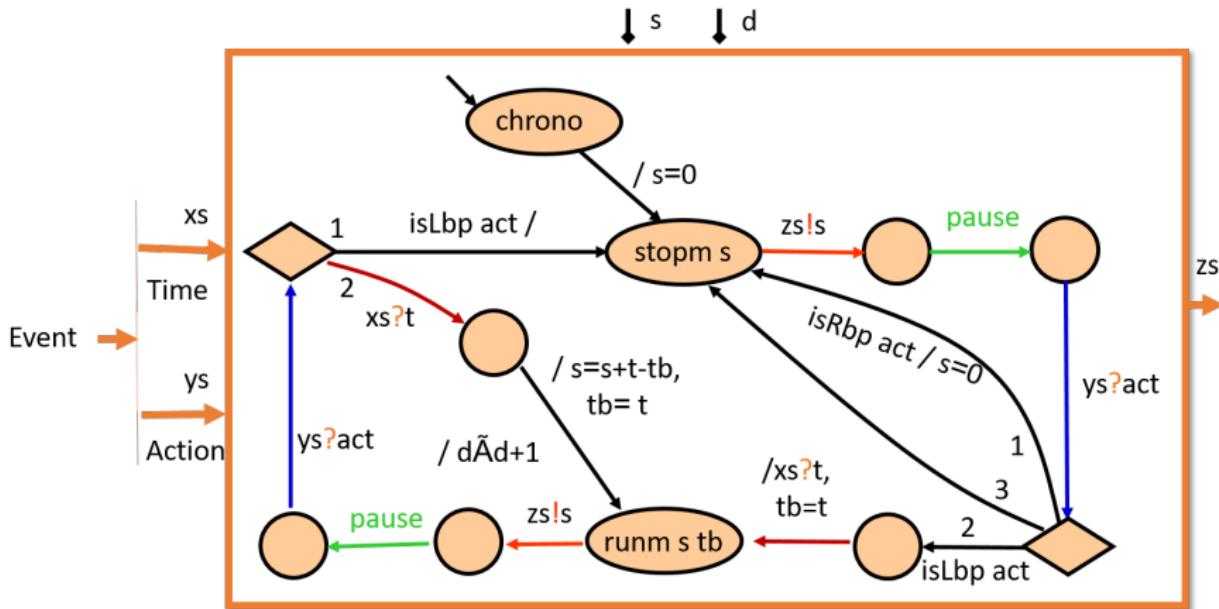
react $ rdf_run chronogr             -- running the animation
```

Stopwatch (simplified)

```
stopm :: Double → KP Event Double
stopm s =
  vHd hFlow ! s $ r_pause $
  vHd hFlow ? λ(act,_) →
    if isRbp act then stopm 0
    else if isLbp act then (vHd hFlow ? λ(_,t) → runm s t)
          else stopm s

runm :: Double → Double → KP Event Double
runm s tb =
  vHd hFlow ! s $ r_pause $
  vHd hFlow ? λ(act,_) →
    if isLbp act then stopm s
    else (vHd hFlow ? λ(_,t) → runm (s + t - tb) t)
```

(simplified)



Pairing & Projection -bkup-

In contrast to general arrows, KP also has a **natural product structure**:

```
(&&&) :: KP c a → KP c b → KP c (P a b)
```

```
r fst :: KP (P a b) a
```

```
r snd :: KP (P a b) b
```

```
*> r print 5 $ r nats e »» (r del 2x2 &&& r del inst)
    => <[]:[(*,0)]:[(0,1),(1,2)]:[(2,3),(3,4),(*,5)]:[(4,6),(5,7),(*,8),(*,9)]:...>
```

```
*> r print 5 $ r nats e »» (r del 2x2 &&& r del inst) »» r fst
    => <[]:[]:[0,1]:[2,3]:[4,5]:...>
```

```
*> r print 5 $ r nats e »» (r del 2x2 &&& r del inst) »» r snd
    => <[]:[0]:[1,2]:[3,4,5]:[6,7,8,9]:...>
```

Tensorial Pairing -bkup-

The product structure depends on “lazy tensorial” pairing which permits us to confuse a pair of lists with a list of pairs.

We use the Maybe monad to fill up missing list elements by a dummy value Nothing which is going to be printed as “*”

```
data P a b = P (Maybe a) (Maybe b)
```

```
sfst :: [P a b] → [a]
```

```
ssnd :: [P a b] → [b]
```

```
spair :: [a] → [b] → [P a b]
```

```
*> spair [1,2,3] [1,2,3,4,5,6,7]
```

```
    ==> [(1,1),(2,2),(3,3),(*,4),(*,5),(*,6),(*,7)]
```

```
*> sfst $ spair [1,2,3] [1,2,3,4,5,6,7] ==> [1,2,3]
```

```
*> ssnd $ spair [1,2,3] [1,2,3,4,5,6,7] ==> [1,2,3,4,5,6,7]
```