

**Data Management**

**Challenges**

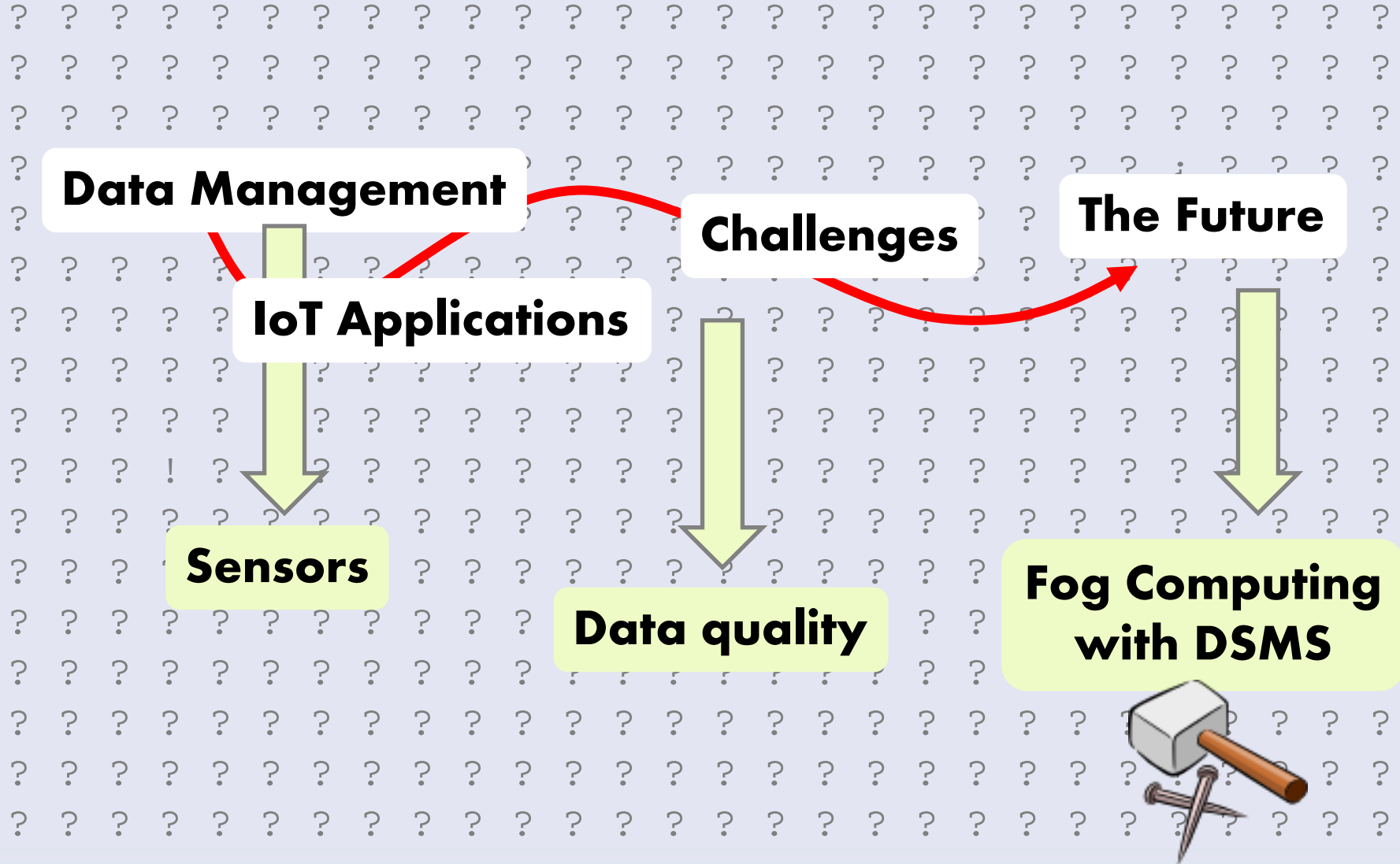
**The Future**

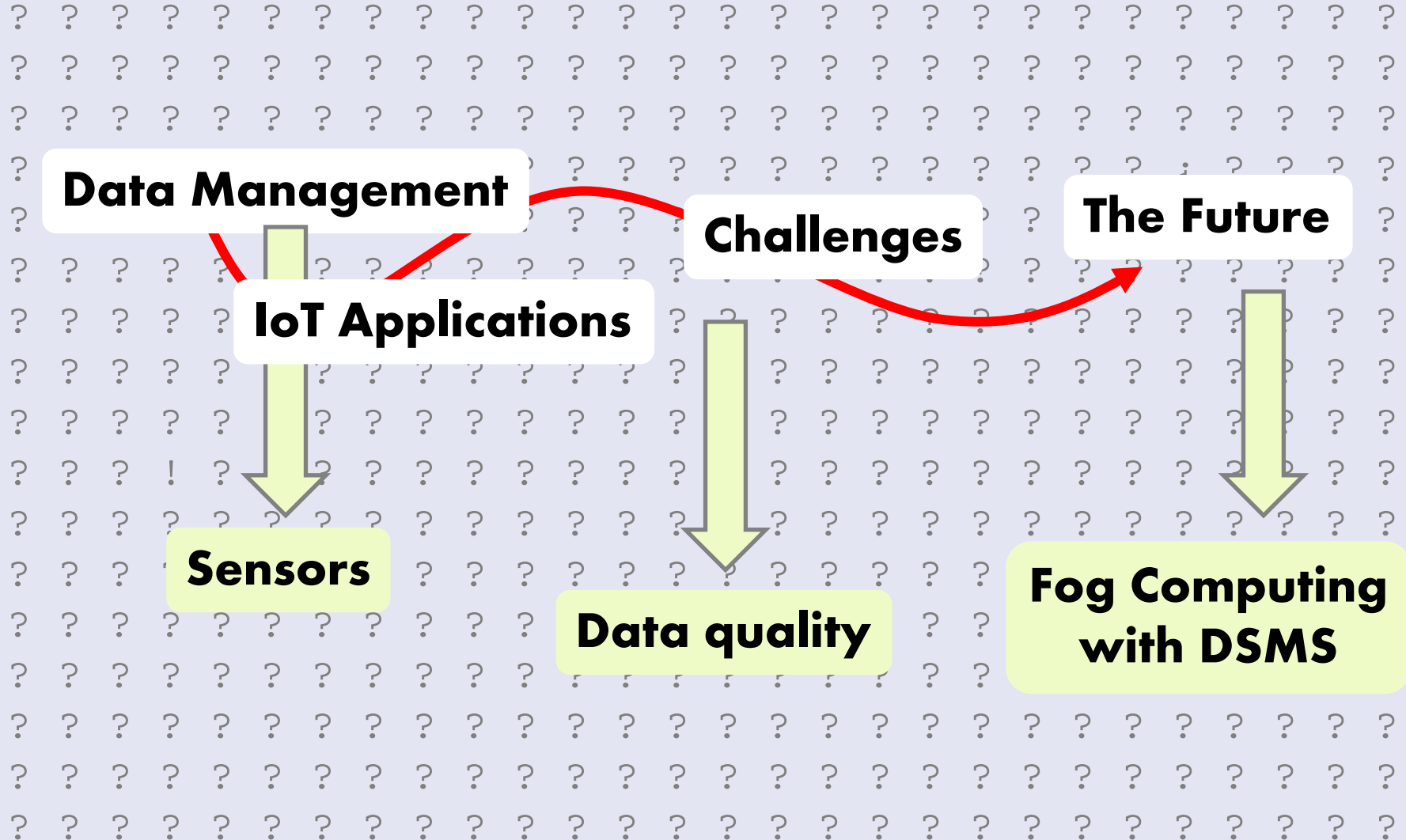
**IoT Applications**

# Data Management Challenges for Future IoT Applications

2th IEEE International Symposium on Service-Oriented System Engineering  
March 26 - 29, 2018. Bamberg, Germany

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Chair of Computer Science, Mobile Software Systems / Mobility  
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# OK Google – What is IOT?

<https://www.google.com/search?q=iot> (images)



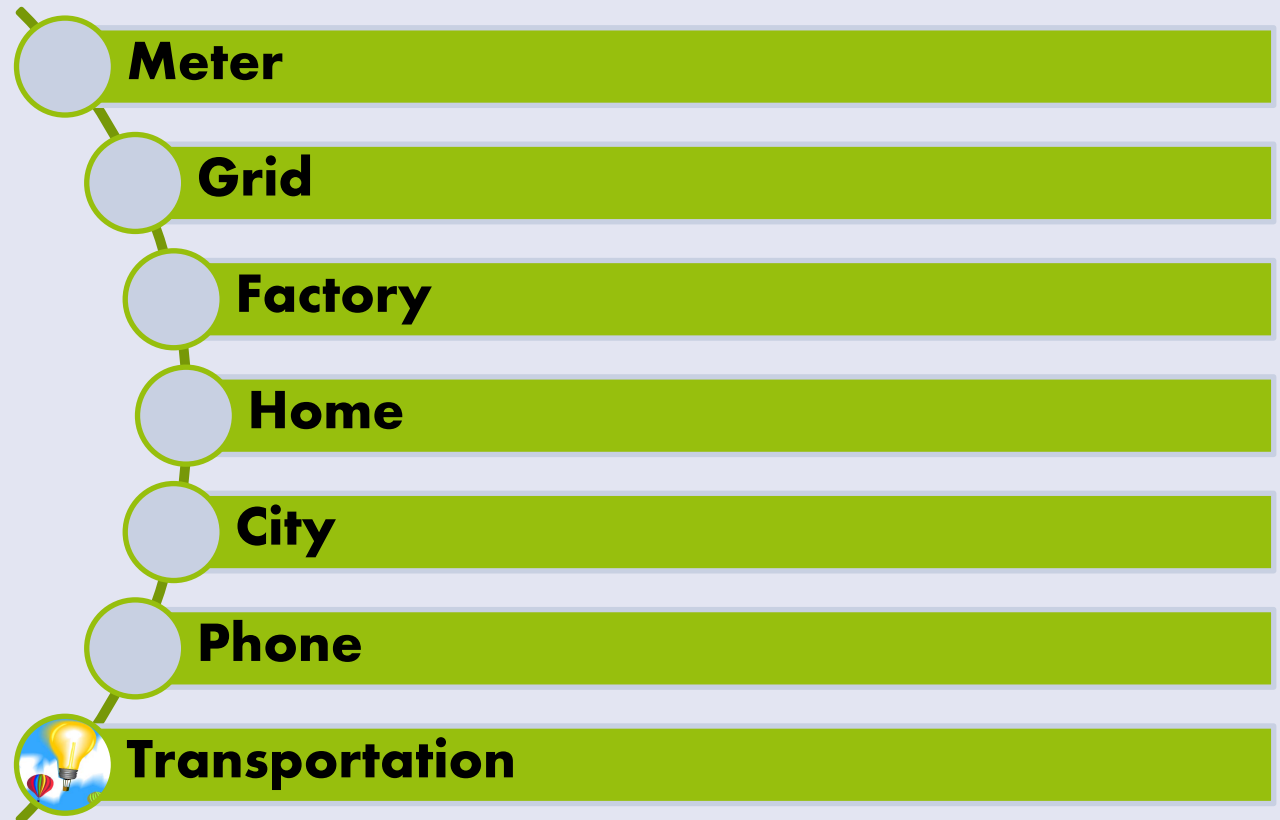
for X in ...

**X**

+ **sensors**

+ **magic**

= **SmartX**



**Realized by: IoT**

Similar challenges in pervasive computing, ambient intelligence, physical computing, ...

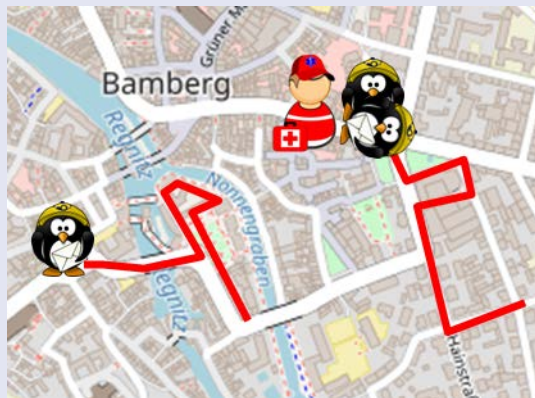


# FutureIoT

- Pan-Bavarian research projects, 02/2018-01/2021
- 10 research partners, >20 industry partners
- Smart city and smart agriculture applications, e.g.:



Long-term evaluation and new services with inductive parking sensors



Privacy-aware delivery tracking (with safety and security features)



Environmental sensing – stationary and mobile

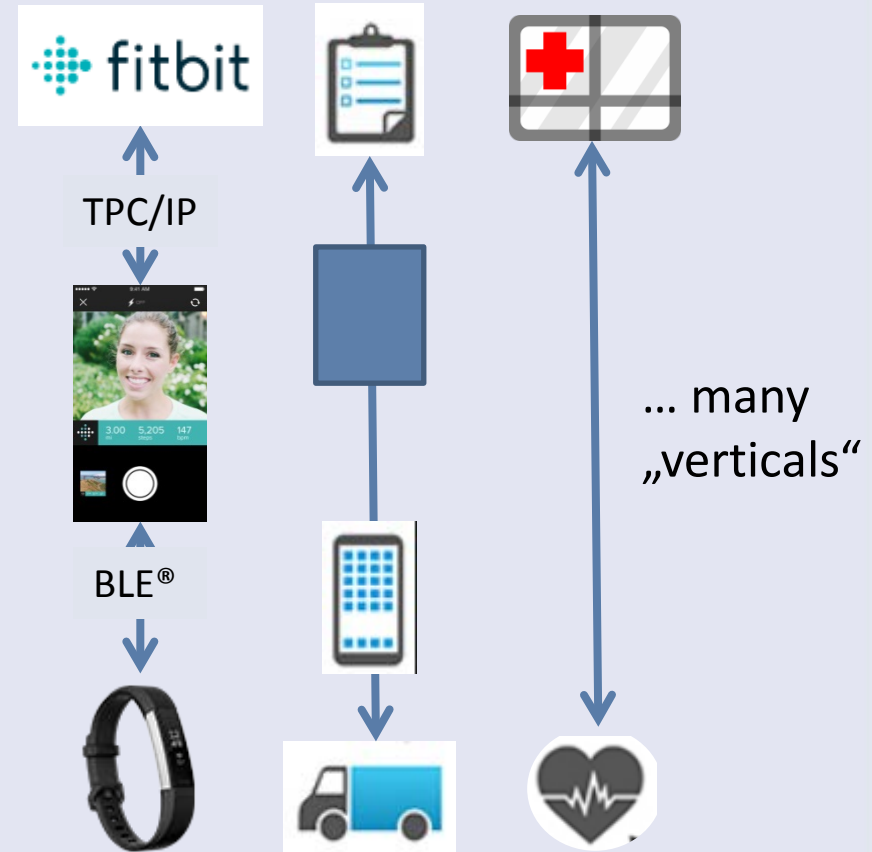


Activity recognition for cows (to detect abnormal behaviour)

## Vision



## Reality

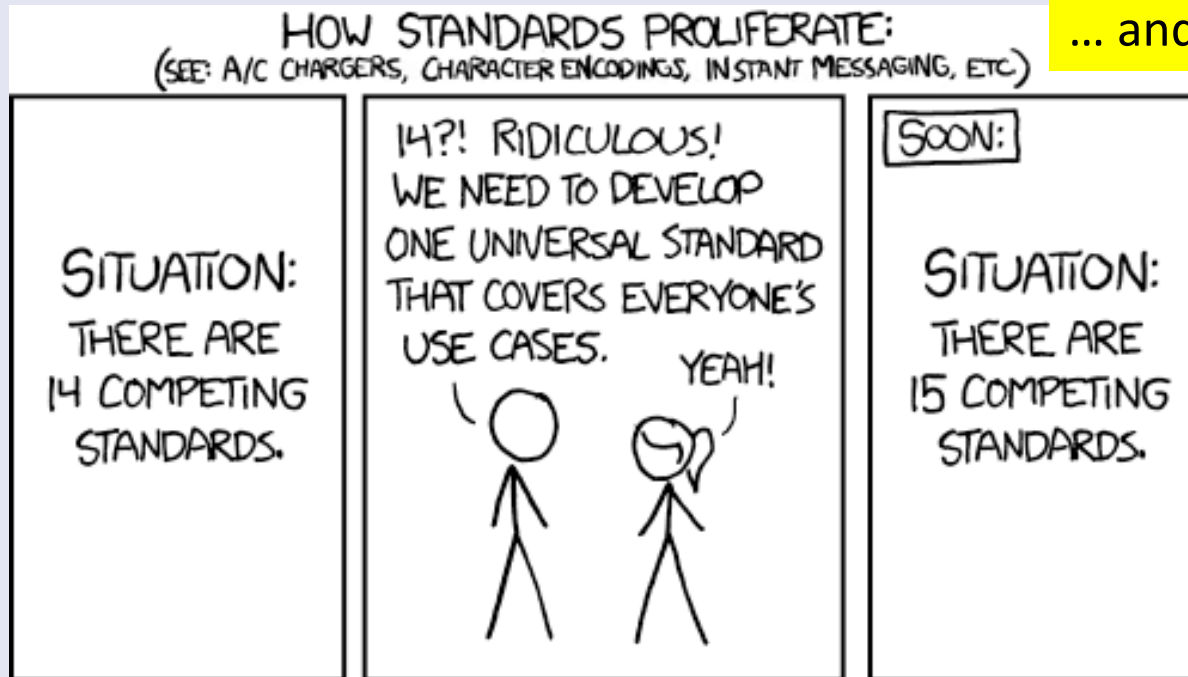


- Shouldn't we help with a standard?



„The nice thing about standards is that you have so many to choose from.“

A. Tanenbaum, *Computer Networks*, 2nd ed., p. 254



<https://xkcd.com/927/>



- Shouldn't we help with a standard?
- From a systematic mapping study [1] on 35 studies on IoT and Cloud:



„The nice thing about standards is that you have so many to choose from.“

A. Tanenbaum, *Computer Networks*, 2nd ed., p. 254

- 15 provide Software as a Service (SaaS)
- 13 provide Platform as a Service (PaaS)
- 10 provide Infrastructure as a Service (IaaS)
- 1 provides Network as a Service (NaaS)
- 2 provide Sensing as a Service (SaaS)
- 2 provide Sensing and Actuation as a Service (SAaaS)
- 1 provides Smart Object as a Service (SOaaS)

On 28.3.18, 123 IoT Platforms are listed on Postscapes.

<https://www.postscapes.com/internet-of-things-platforms/>

[1] E. Cavalcante *et al.*, “On the interplay of Internet of Things and Cloud Computing: A systematic mapping study,” *Computer Communications*, vol. 89–90, pp. 17–33, Sep. 2016.

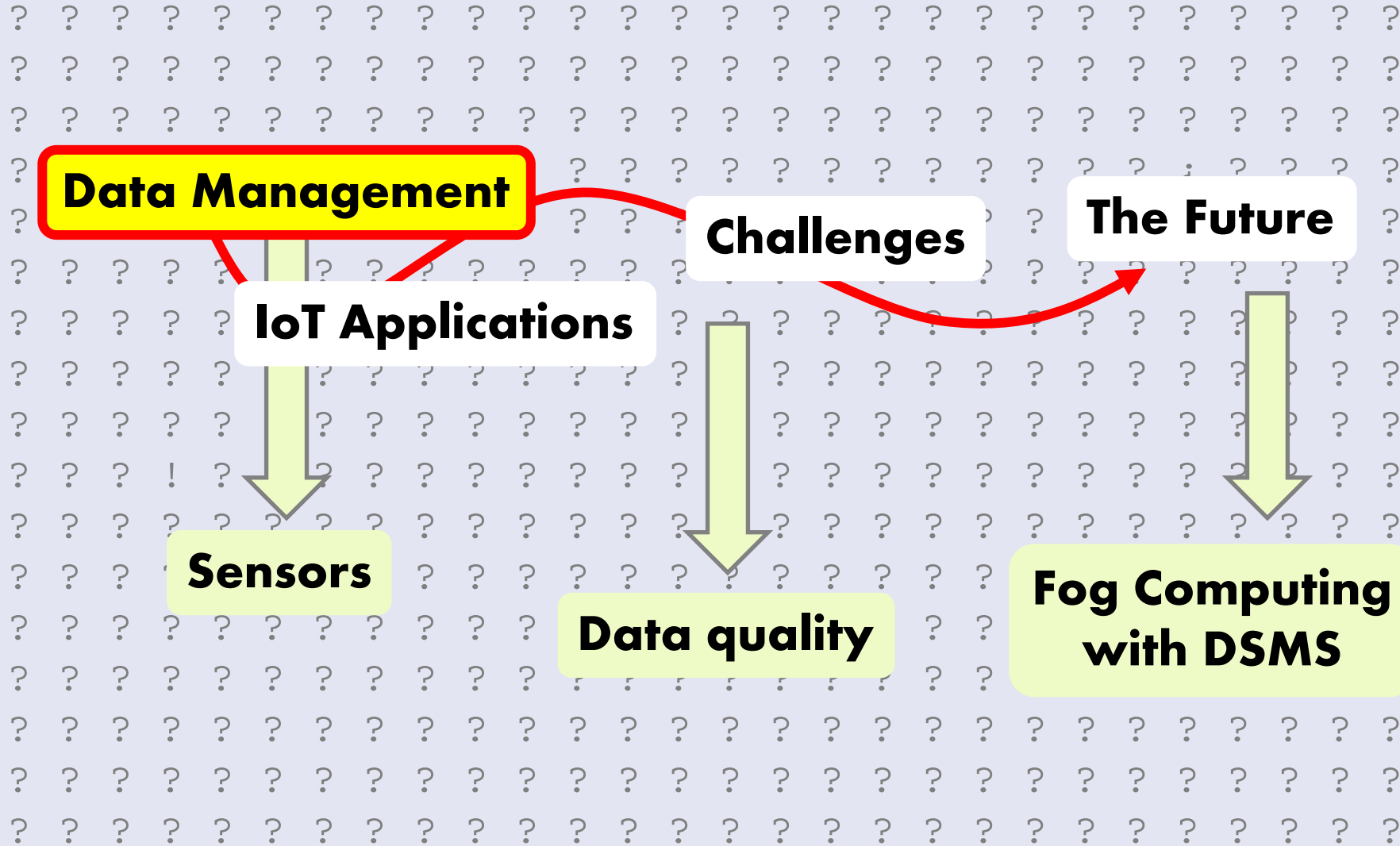


Bild: eili60 / pixelio.de

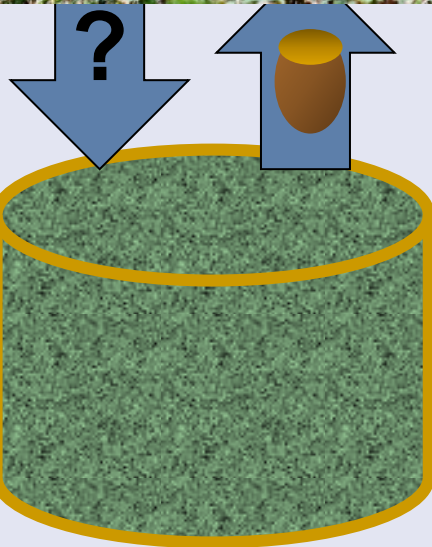
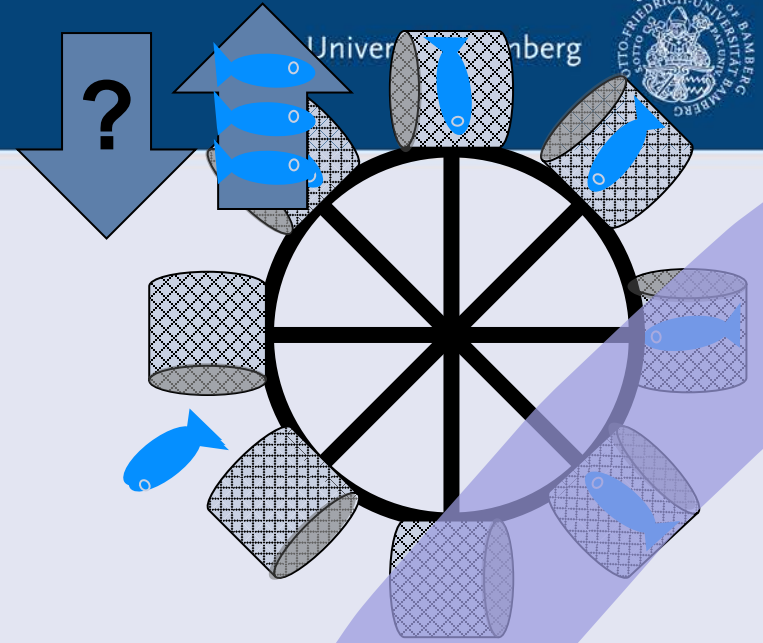


Bild: Ronny Senst / pixelio.de

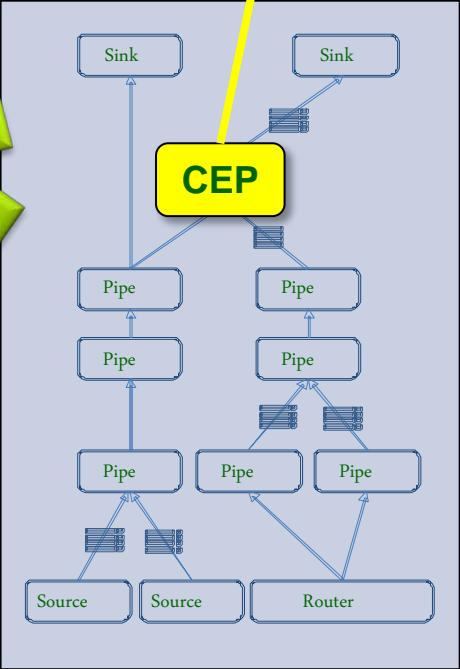


- Programming abstraction
  - Declarative: Query
  - Functional: Data flow graph
    - Enables query optimizations
    - Better maintenance of systems
- Using a DSMS on data streams is like using a DBMS instead of files
- Easy to combine with complex event processing (CEP)
- Parallel execution of operators in graph → no shared memory
- Data streams can be unbounded:  
Issues with sorting, joins, aggregation
  - Approximate answers
  - Window semantics

```
SELECT ego.pos  
RANGE 10 second  
radar RANGE 15  
WHERE ego.speed > 30 AND  
radar.speed > 30  
AND s2.po
```

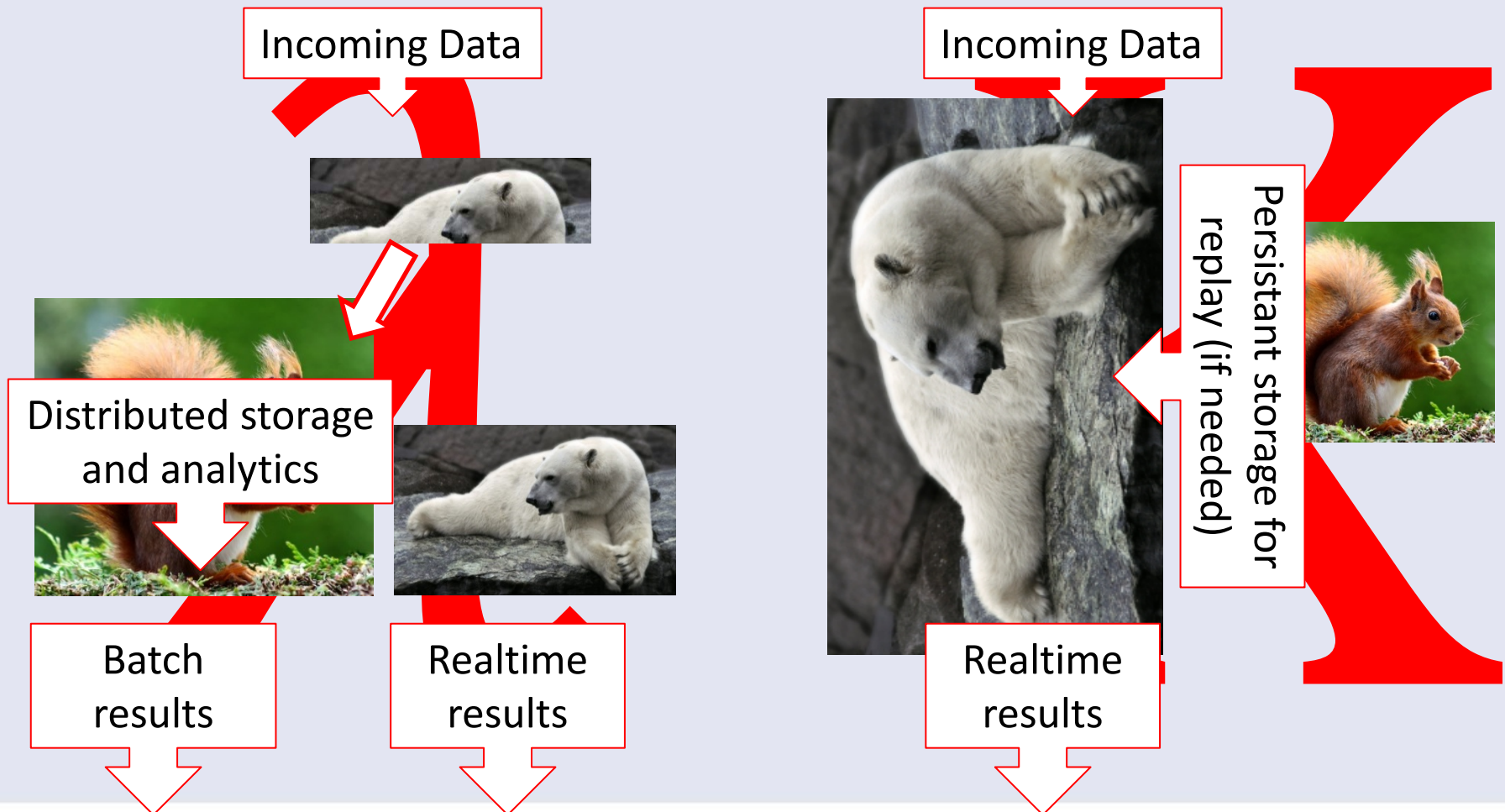
**Some DSMS provide CEP operators**

```
stream<uint64 current  
sensorId, uint8 sen  
measureValue1, floa  
float64 distanceV,  
uint8 speed, uint8  
direction, uint64 t  
Aggregate(HigherGPS
```

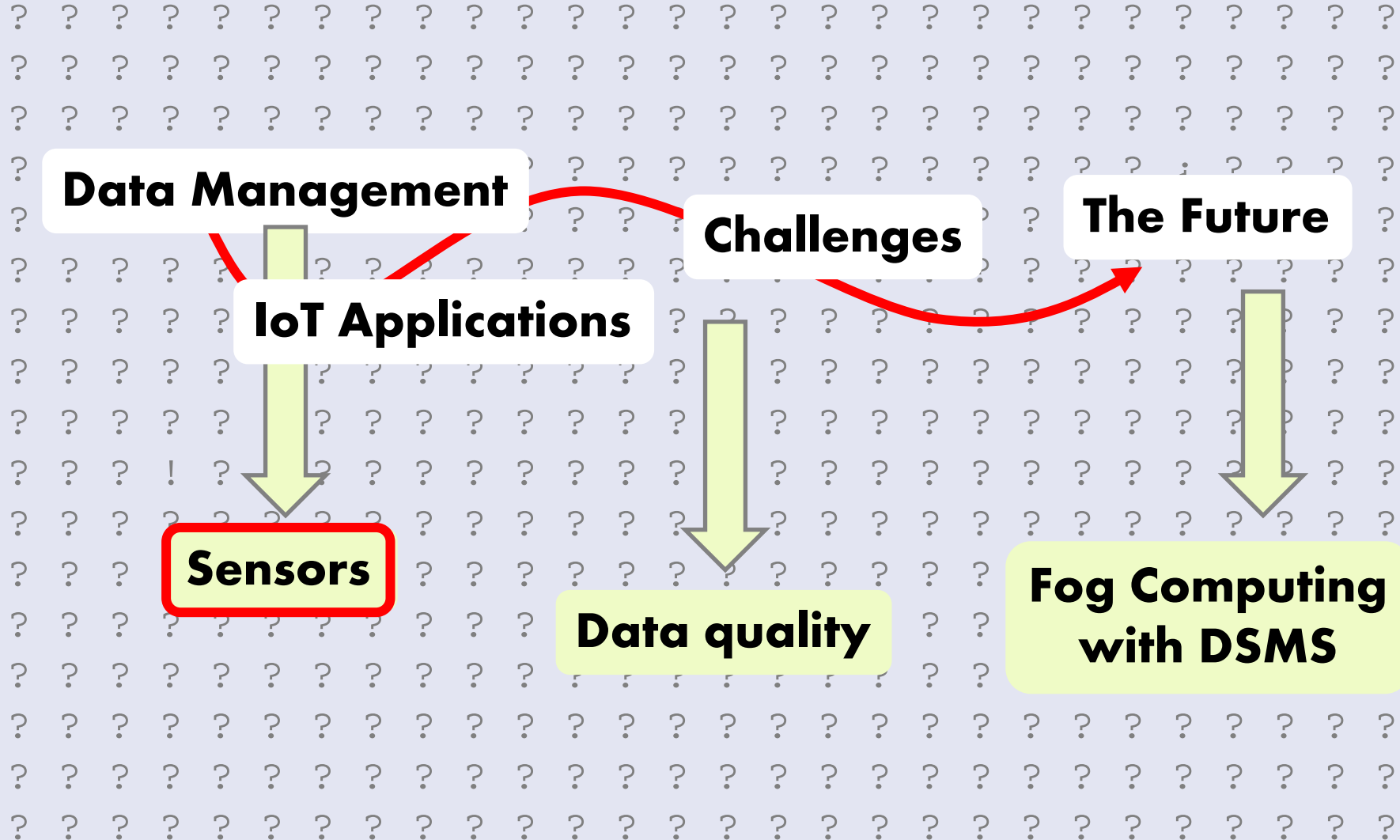


```
{window HigherGPS :  
param groupBy : sensorTypeID ,  
output MapGPS : avgSpeed = Average(speed)  
;}
```

- Suggested architectures for big data stream processing







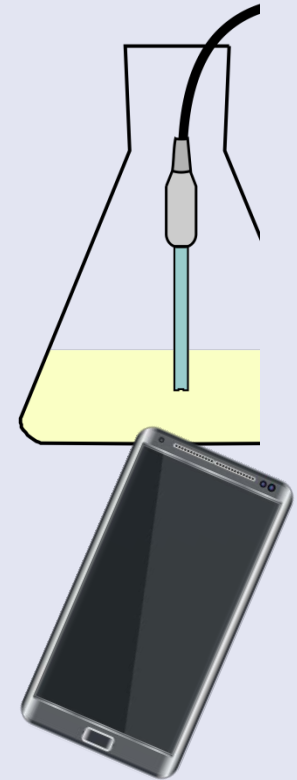


A **sensor** is an electronic component, module, or subsystem whose purpose is to detect events or changes in its environment and send the information to other electronics, frequently a computer processor.

<https://en.wikipedia.org/wiki/Sensor>

- Technical systems can achieve situational awareness by using data from sensors
- However, sensor data is often ...
  - incomplete (not everything can be sensed)
  - late (results do not arrive in time)
  - inaccurate (values are not exact)
  - mobile (sensed by moving systems)
- To make things worse, sensor data needs to be interpreted ... and interpretations can cause further errors

- Sensors implement transfer function:
  - Input: A state of the observed phenomenon
  - Output: A signal (analog or digital) → sensor data
  - Most sensors have a linear transfer function
- Sensitivity of a sensor:
  - How much does the sensor output change when the input changes?  
→ Slope of the transfer function
- A sensor system contains:
  - One or many sensors
  - A processing unit (fixed or configurable) to derive data from the sensor signal
  - A communication unit (wired or wireless) to transfer the data to an other system



- Phenomenon:
  - Physical? (Light, noise, acceleration, radio signals, ..)
  - Chemical? (Substances in gas or fluids)
  - Social? (Behaviour, communication, ...)
  - Technical? (Proper operation, ...)
- Measurement:
  - Direct or derived?
  - Latency?
- Redundancy:
  - One sensor or many?
  - Same sensors or different?
- Installation:
  - Static or mobile?
  - Wired or wireless?
  - One-hop or multi-hop?
  - Calibration?
- Aging:
  - Battery?
  - Saturation?
  - Re-calibration?
- Cost <-> Quality – Tradeoff!

- Format:
  - Structured (e.g. (Timestamp, Value), or (Value, Value, Value))
  - Unstructured (e.g. image stream (video) or audio stream)
  - Semi-structured (e.g. photo + DXF meta data (timestamp, location, resolution, ...))
- Semantic levels:
  - Raw: just the signal
  - Feature: a typed attribute of an entity, e.g. the location
  - Object: multiple attributes grouped together for an object
  - Situation: a complex situation was detected

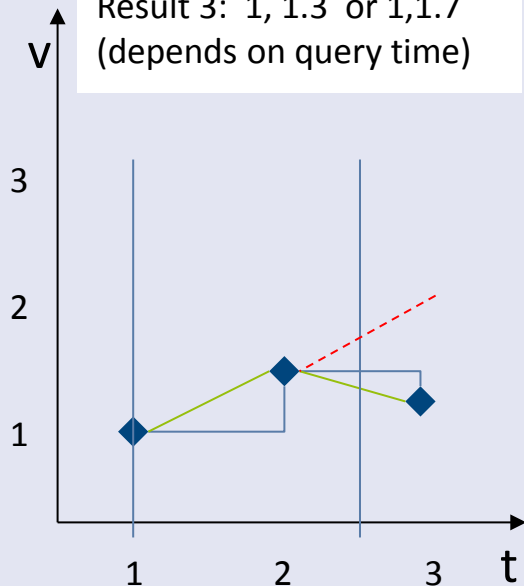
→ Higher levels are often results of sensor data fusion
- Validity: How long is the sensor value valid?
  1. Only at timestamp
    - if sensor sends with fixed frequency
  2. Fixed until next data comes in
    - if sensor sends when value deviates from last value by threshold
  3. Changing according to model
    - if sensor sends when value deviates from a function of time
    - „dead reckoning“ → often used for moving objects (but can be applied to other phenomena)

```
select t, v from sensordata
where t = 1 or t = 2.5
```

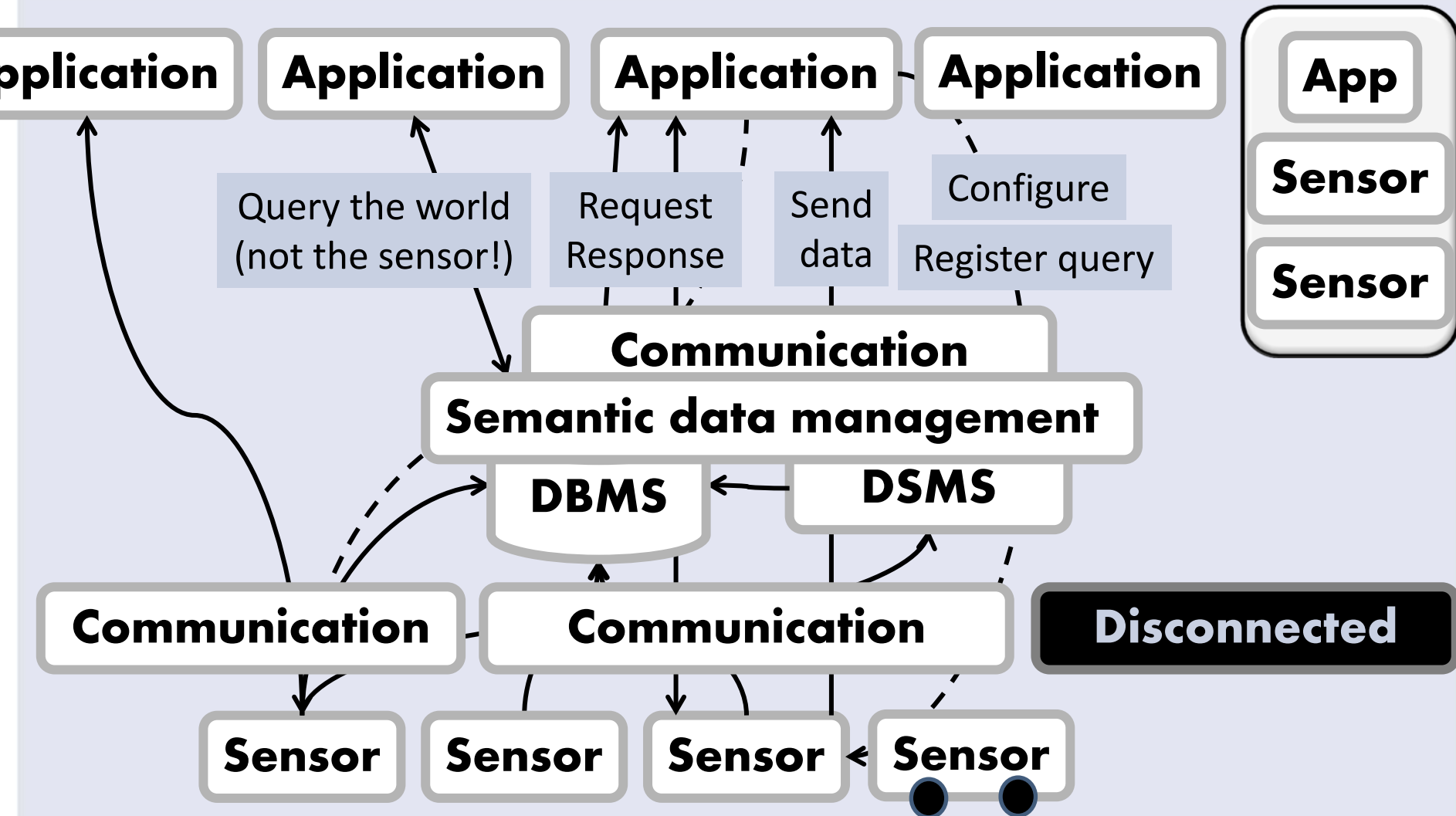
Result 1: 1, NULL

Result 2: 1, 1.5

Result 3: 1, 1.3 or 1,1.7  
(depends on query time)



# Evolution of a sensor-based system



# Evolution of a sensor-based system

Application

Application

Application

Application

App

Sensor

Sensor

**Maintenance hell**

**High redundancy, no reuse**

**Unclear quality**

**Unclear security**

...

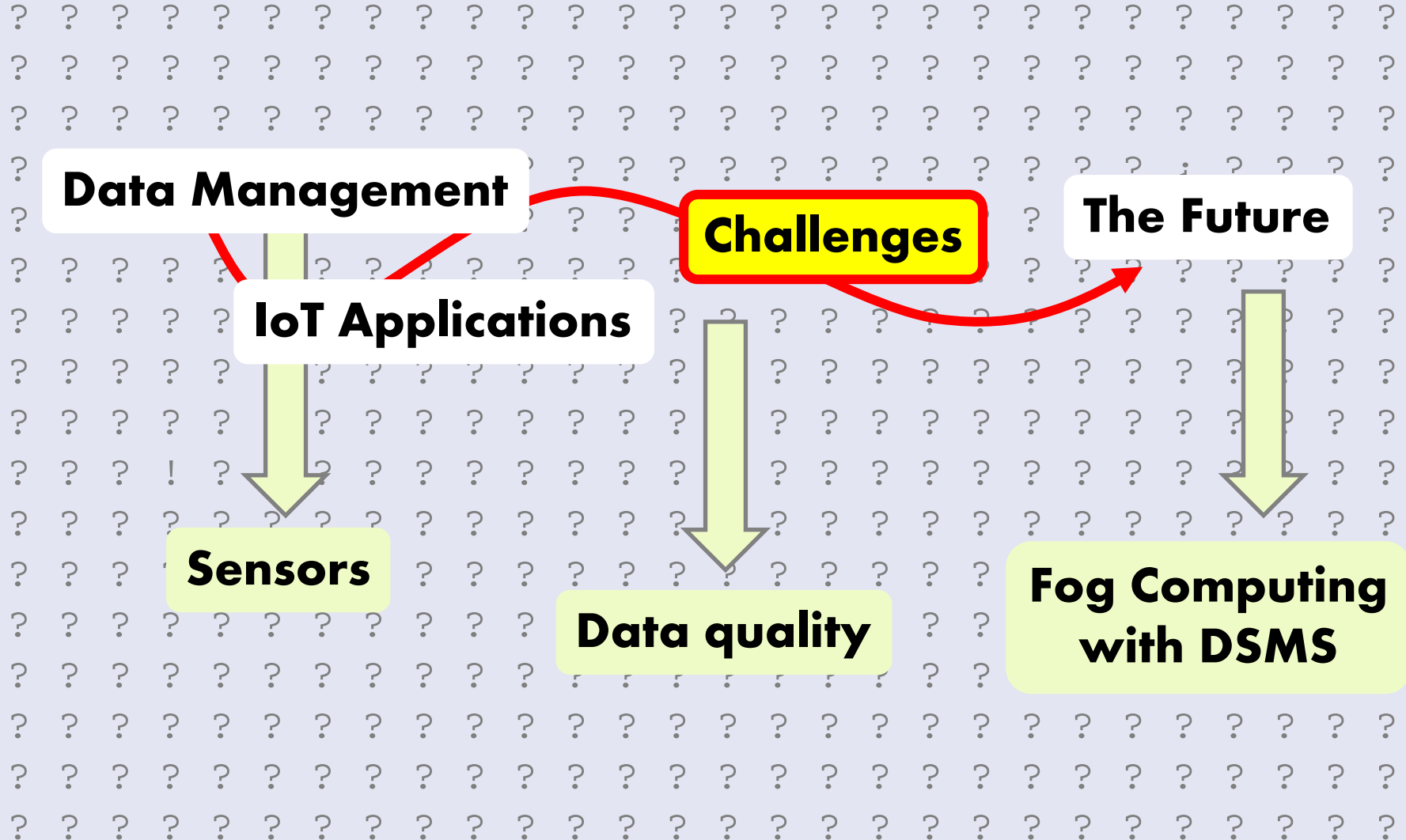
Sensor

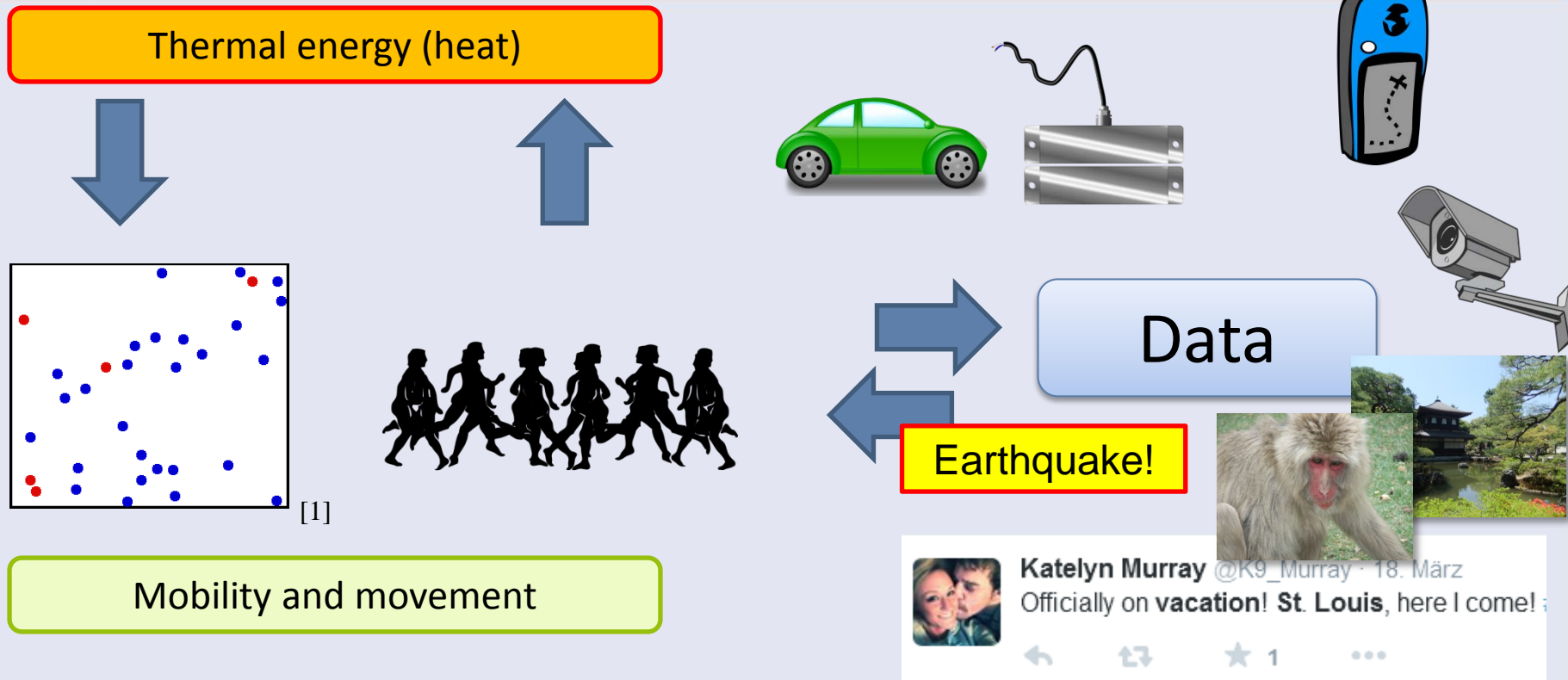
Sensor

Sensor

Sensor







2006, [http://ana.blogs.com/maestros/2006/11/data\\_is\\_the\\_new.html](http://ana.blogs.com/maestros/2006/11/data_is_the_new.html), retrieved 21.3.2015

## Data is the New Oil

By Michael Palmer

"Data is the new oil!" [Clive Humby](#), ANA Senior marketer's summit, Kellogg School.

Data is just like crude. It's valuable, but if unrefined it cannot really be used. It has to be changed into gas,

# Data is the new crude oil ...

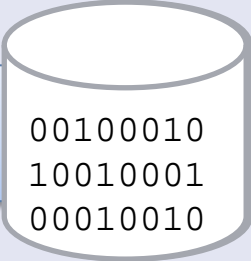
... it needs to be refined to be valuable.

Crude oil



- Fuel oil → mobility
- Chemical products:
  - pharmaceuticals → health
  - fertilizers → increase growth
  - pesticides → kill insects
- ...

Data



```
00100010
10010001
00010010
```

Information

Knowledge

Action

## On representing situations for context-aware pervasive computing: six ways to tell if you are in a meeting

Seng W. Loke

Caulfield School of Information Technology  
Monash University, VIC 3145, Australia  
swloke@csse.monash.edu.au

### Abstract

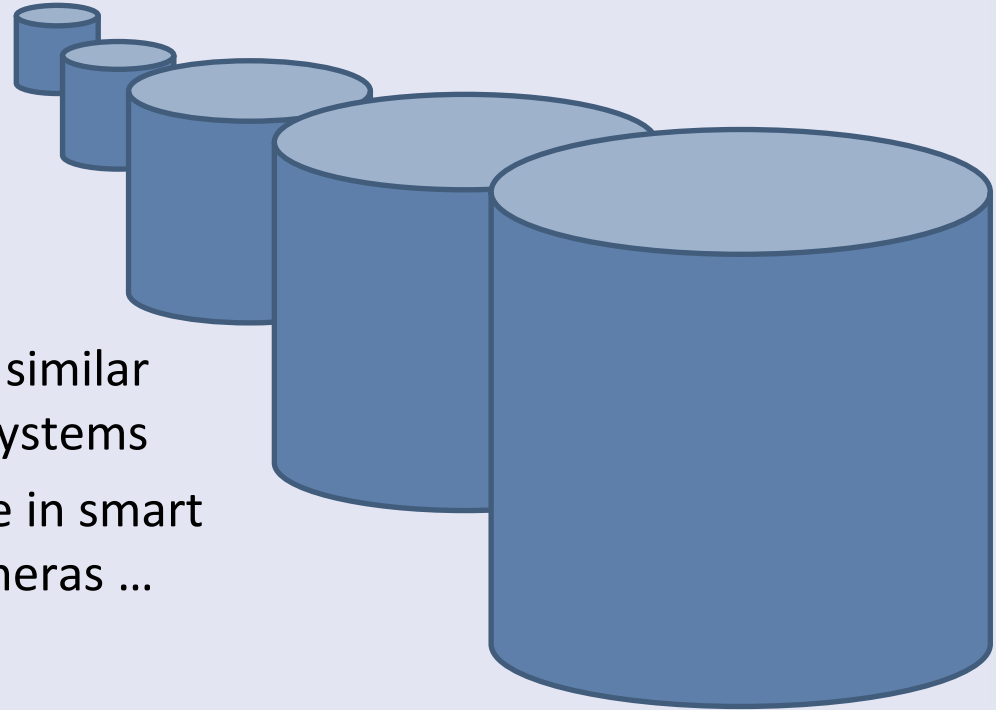
*Context-aware pervasive systems are emerging as an important class of applications. Such work attempts to recognize the situations of entities. This position paper notes three points when modelling situations: (1) there can be multiple ways to represent a situation; (2) a situation can be viewed as comprising relations between objects and so recognizing a situation boils down to determining if a prescribed set of such relations hold or not hold at that given point in time; and (3) situations can be represented in*

to an appropriate mode (e.g., see that I am in a meeting and put itself to silent mode). One could enumerate a set of typical situations (or situation types) which the phone can be in and have rules to act appropriately in those situations. There would be a need to have some formalism to represent these typical situations in terms of readings from sensors - we are in effect labelling a collection of sensor readings with an interpretation that they represent some situation.

In this paper, we explore an approach to recognizing and reasoning with situations from the perspective of knowledge engineering. We (as a domain expert) create explicit rep-

S. W. Loke, "On representing situations for context-aware pervasive computing: six ways to tell if you are in a meeting," 2006, pp. 35–39.

- Googles self-driving car: nearly 1MB data per second<sup>1</sup>
  - Per day: 85 GB
  - Per year: ~30 TB
  - If 10% of the cars would be like this, or 50%, or ... (> 1 Billion cars on the world)
  - ... not only by self-driving cars, similar for advanced driver assistant systems
  - ... plus data from infrastructure in smart cities, like induction loops, cameras ...



# → Big Data!

<sup>1</sup>Bill Gross, Founder and CEO of Idealab

<https://www.linkedin.com/today/post/article/20130502024505-9947747-google-s-self-driving-car-gathers-nearly-1-gb-per-second>

- Many definitions, often by a number of 3-5 "V" challenges:

**Volume** A lot of data (amount varies)

**Variety** Data differs in structure

**Variability** Structure changes

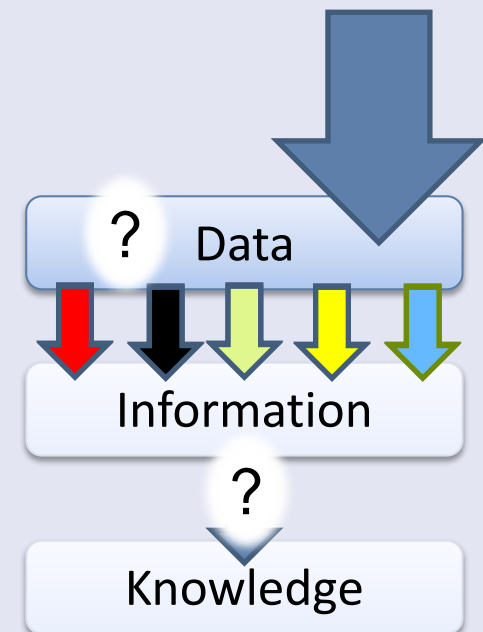
**Velocity** Many updates

**Veracity** Unclear source or quality

Not in list of challenges:

**Privacy**

(analysis of sensible data, how to adhere to legal / societal constraints?)





- More "velocity", less "volume"
- Direct processing
  - Online, (hard/soft) real time, "right time"
- More information, less data
  - Enrichment of data streams
    - E.g., product information for an RFID tag
  - Interpretation and reasoning
    - E.g., classification ("this is a car")
  - Data cleansing
    - Remove redundancy, anomaly detection
- Online quality assessment
- Enables built-in privacy methods
  - Online pseudonmization and anonymization
  - Data economy
  - Certify and/or publish your query plans

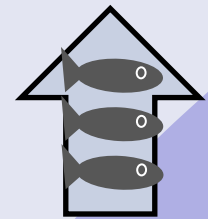
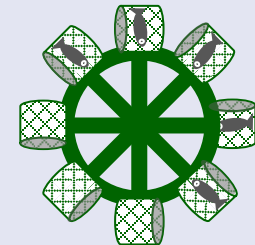
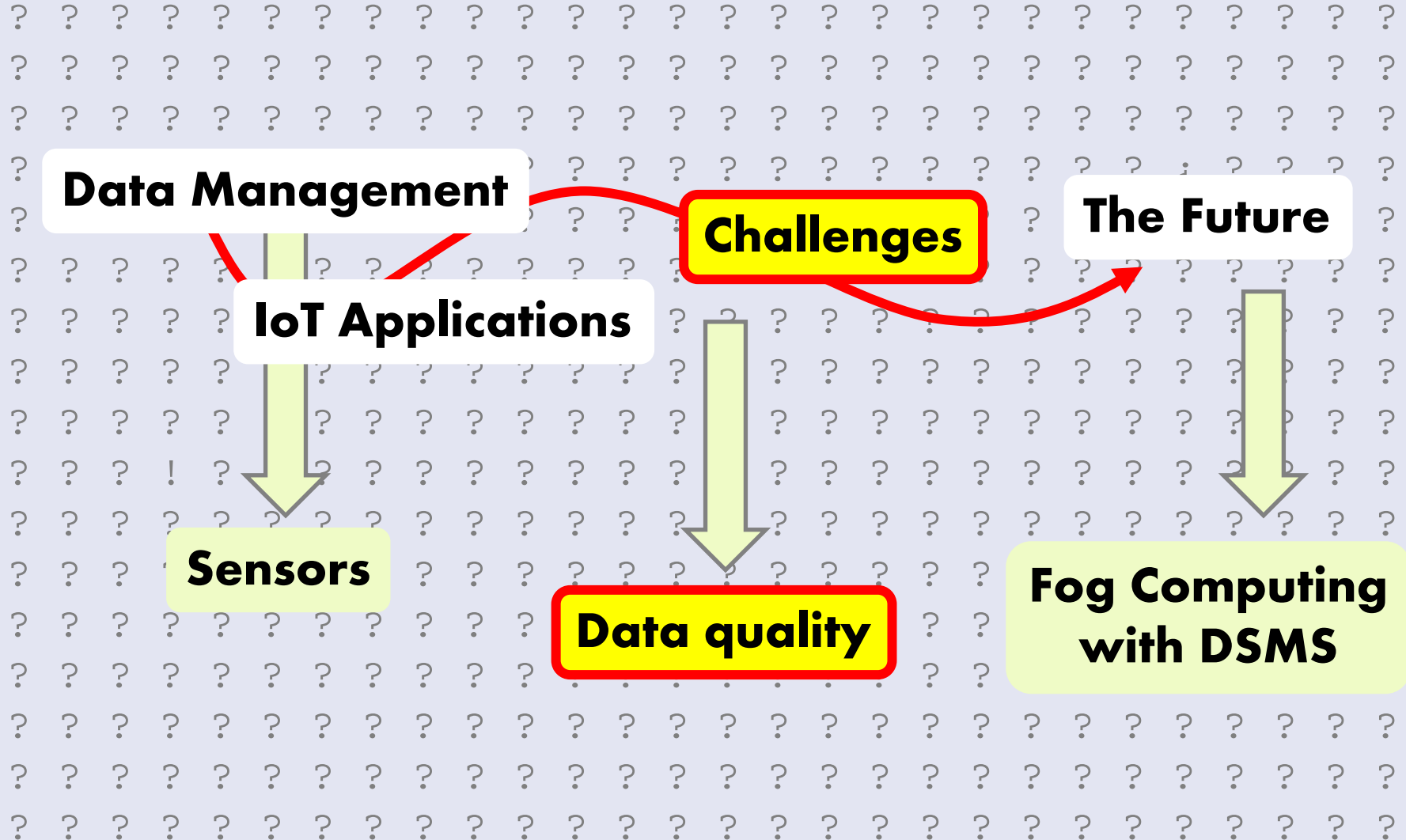


Bild: Ronny Senst / pixelio.de







- Data source
    - Measurement method, e.g. low frequency of sensor for fast moving objects
    - Environment, e.g., temperature too high for good measurements
    - ...
  - Data processing
    - Wrong training data for classifier
    - Over-simplified models or missing concepts
    - Not enough input data for algorithm
    - Stale models (due to concept drift)
    - ...
  - Some can be detected after installation of system, some occur later
- Decisions based on inprecise data

Goal: programming abstractions for dealing with non-perfect data

Approach:

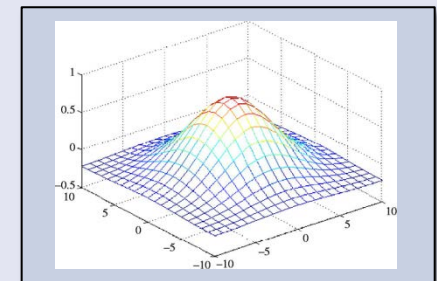
1. develop unified data model to represent data quality
2. consider data quality in operators

→ data management can attach combined quality metadata to result

• How to determine data quality and correlations?

- given by data source / sensor (e.g., accuracy)
- given by algorithm (e.g., confidence)
- learned by observation (requires redundancy)

→ store in sensor relationship model



**type (probability)**

bicycle (0.8)

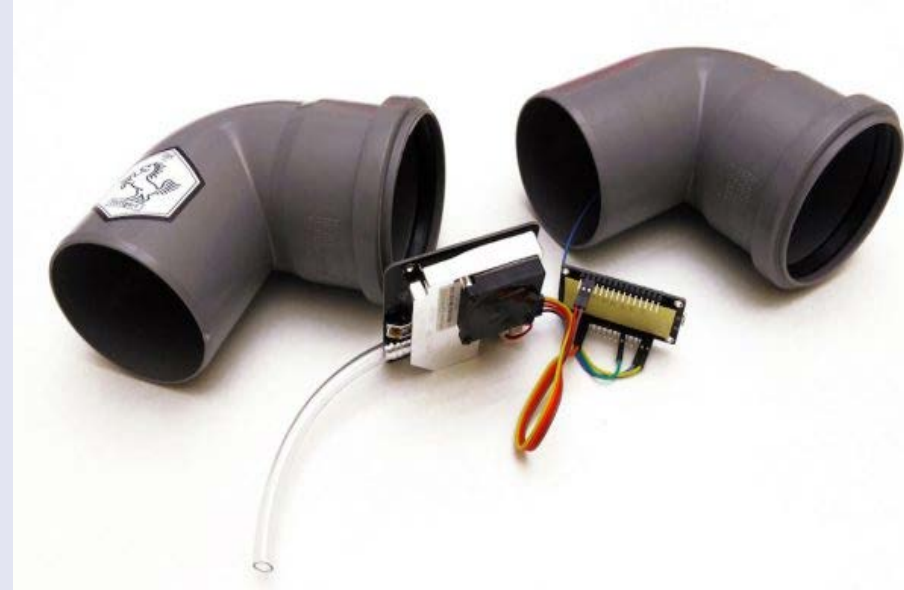
pedestrian (0.1)

other (0.1)

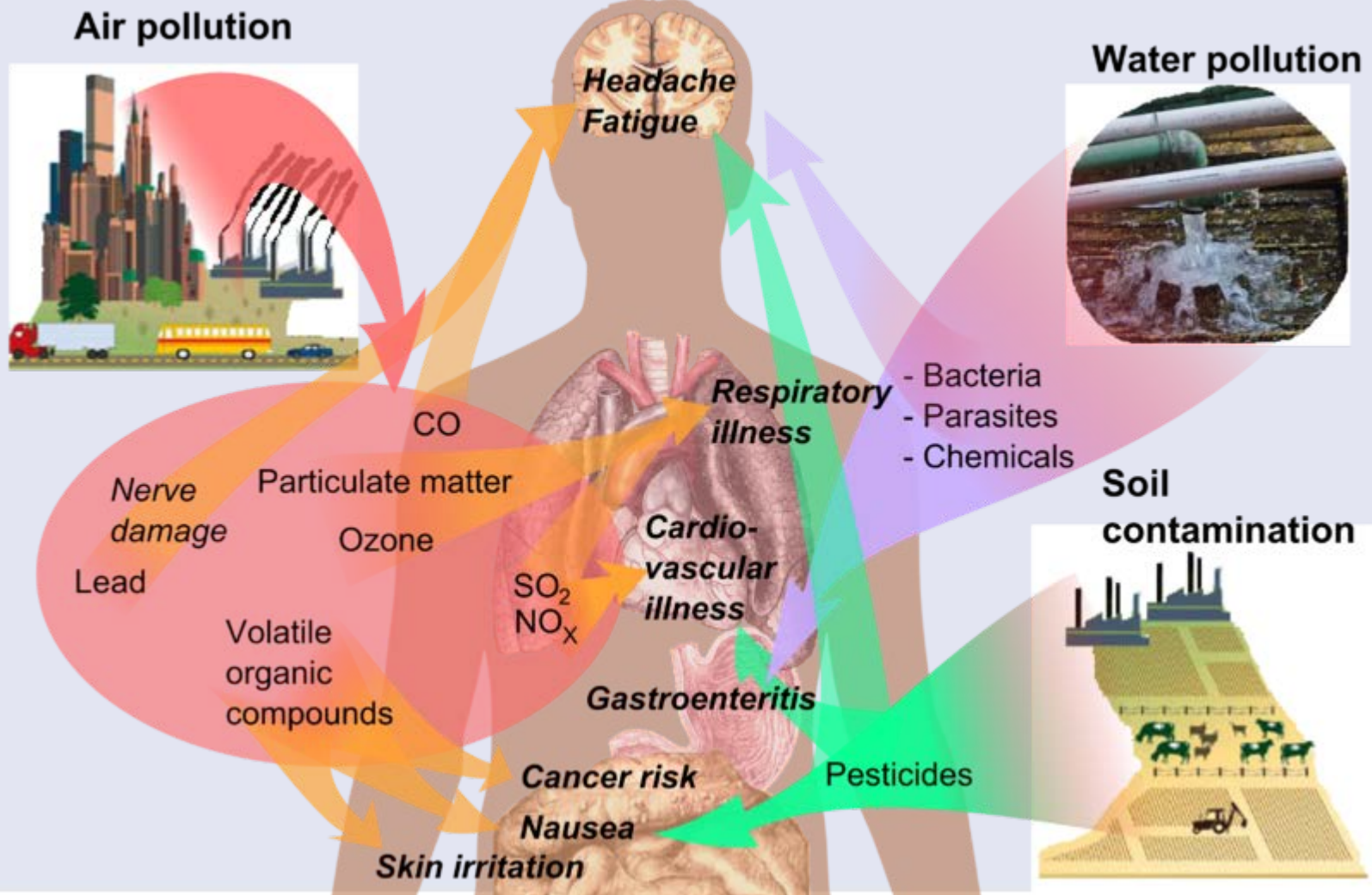
# Example:

## Citizen Science Project luftdaten.info

- Founded by Open Knowledge Lab Stuttgart
  - A group of ten people working mostly on *Citizen Science* projects
- Start: June 2015
- Access for all people:
  - Feasible components
  - Easy assembly
  - Regular workshops and talks throughout Germany
- Goals:
  - Monitor the air quality in Stuttgart
  - Involve citizens in the process
  - Increase the coverage to other areas in Germany and other countries



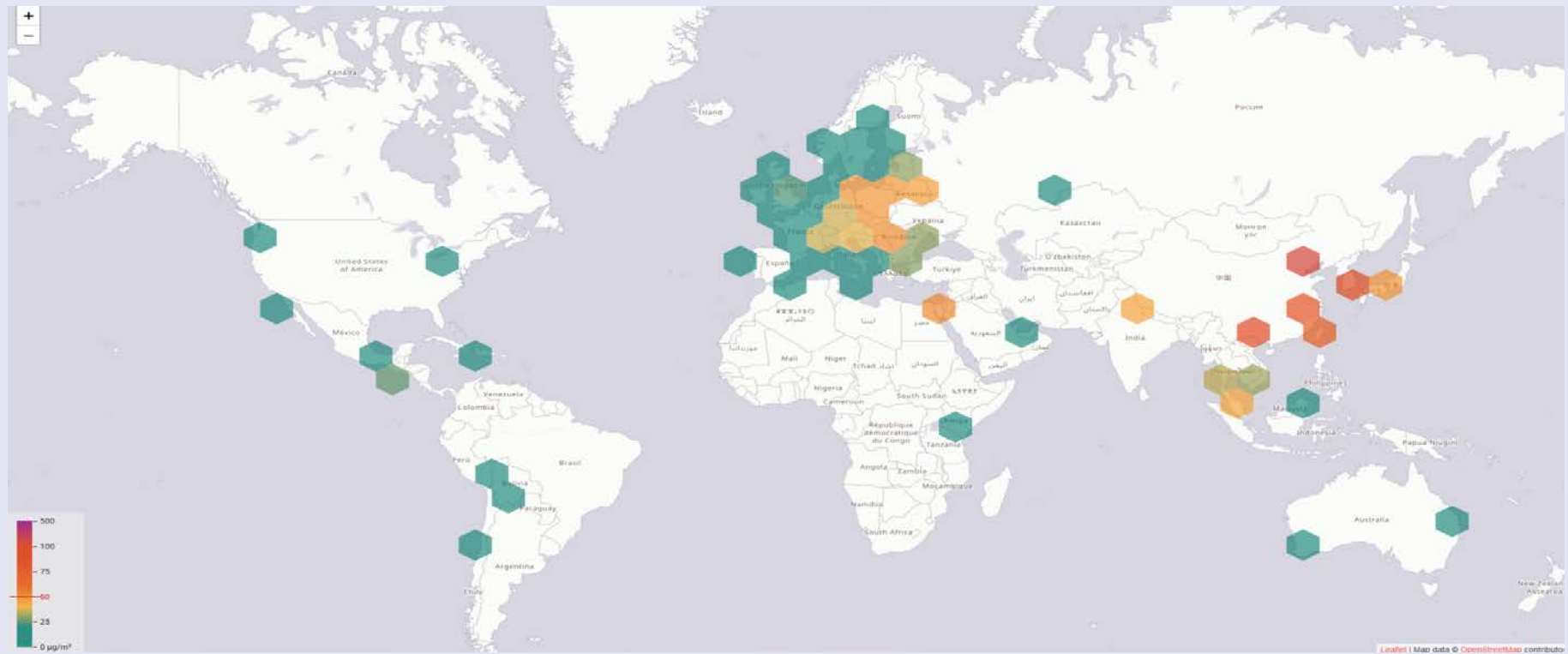
## Health effects of pollution





# Current status of sensor installations

- 4230 registered sensors
- Data from over 15 countries
- Average sensor measurements produced per day:  
~80000 readings (as of 02/2018)

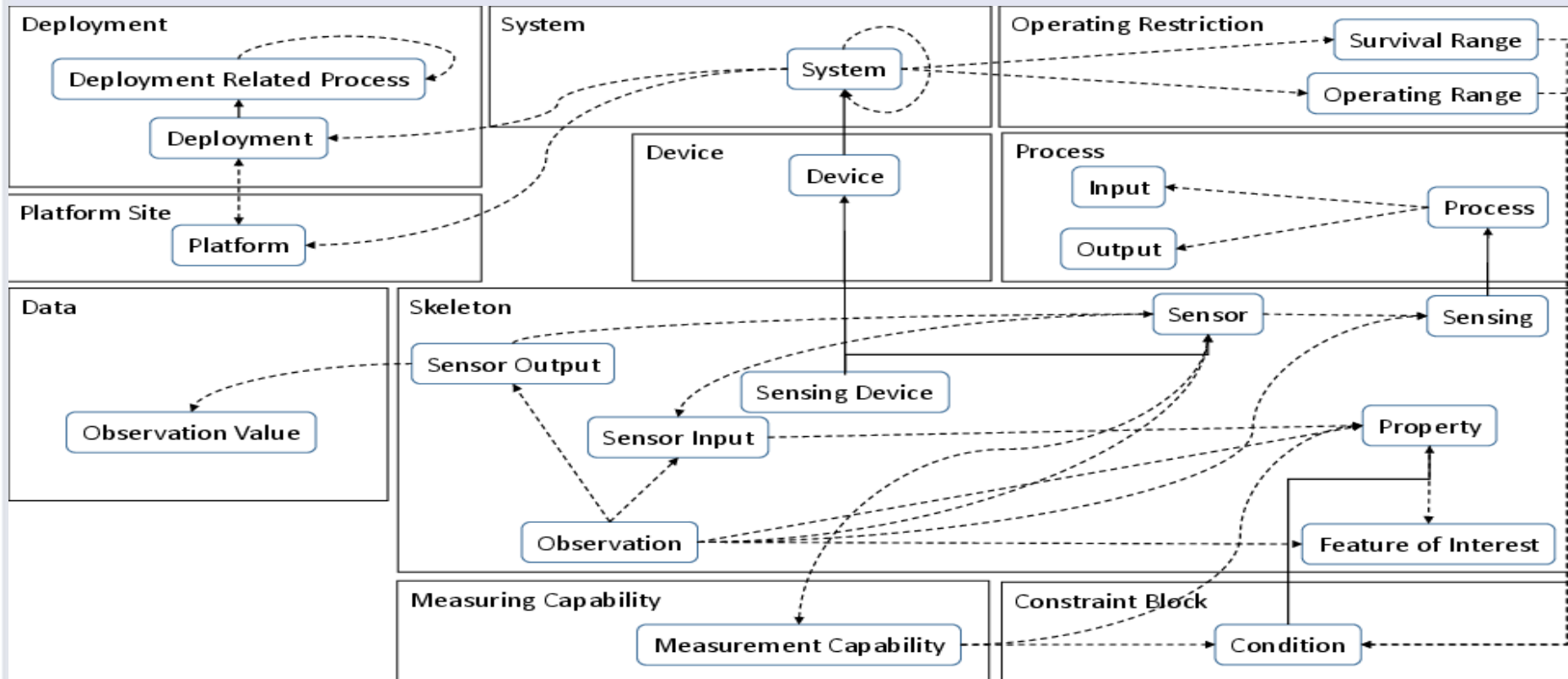




- Sensors can have faulty behaviour and anomalies
  - PM values are no longer reliable when the humidity rises above 70%
  - Some sensors are installed indoors → data leads to wrong conclusions
  - Strange effects might occur later (e.g., spiders in the sensor box)
- Offline detection of the PM quality issues
  - Fusion of the sensor data with data from the neighbouring weather stations
- Online detection of the PM quality issues
  - Use of the on board humidity sensor as a reference
  - Live Stream processing of the sensors with the related weather stations based on the underlying semantic model

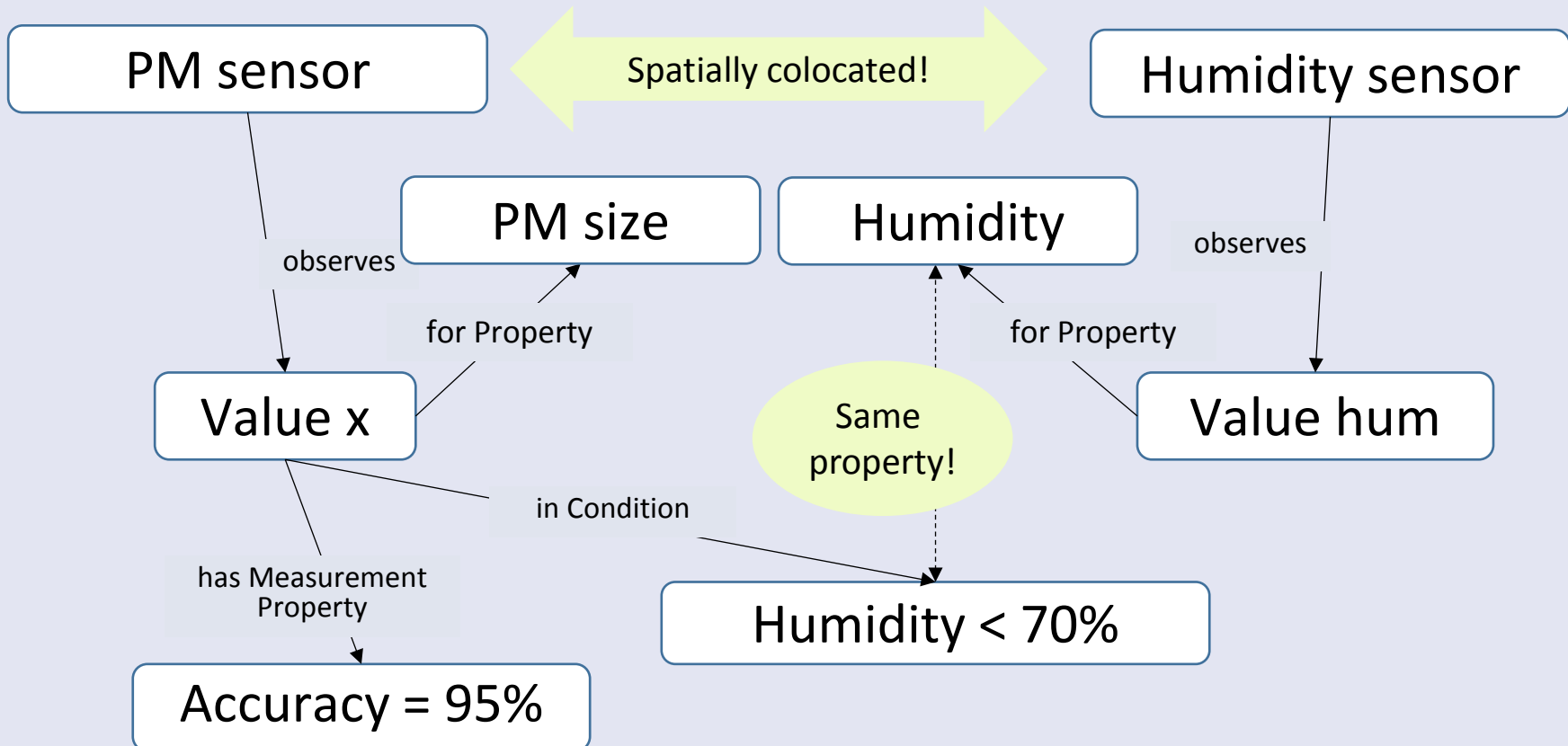


- Created by W3C Semantic Sensor Network Incubator Group (2011) for
  - Syntactic interoperability
  - Semantic compatibility of sensors and their measurements

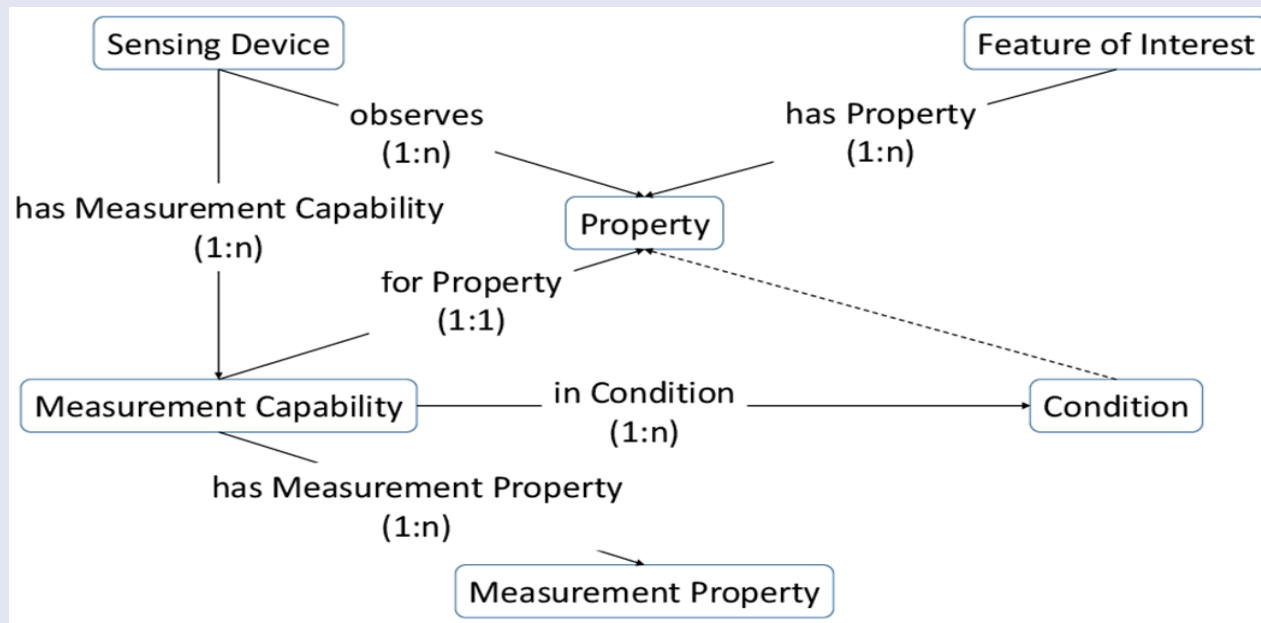


Christian Kuka: Qualitätssensitive Datenstromverarbeitung zur Erstellung von dynamischen Kontextmodellen, PhD, Universität Oldenburg, 2015

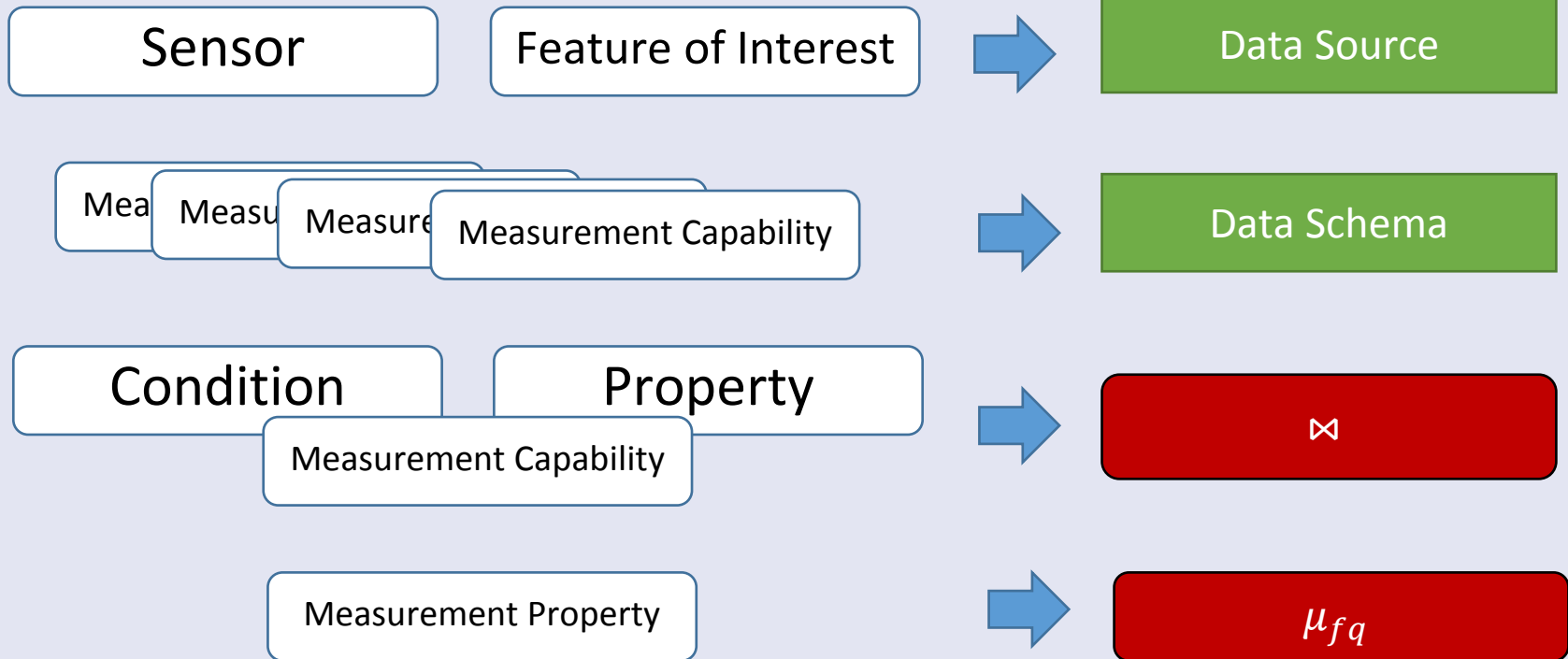
- Measurement capabilities can have conditions
- Conditions can be measured / observed by other sensors!



- Mapping of nodes in the ontology to sources and schemas in a DSMS
  - *Sensors and Feature of Interest to active sources*
  - *Measurement Capability to data stream schemas*
- Transformation of links in the ontology into partial processing queries
  - Conditions are transformed into select predicates and *Measurement Properties* into mapping expressions

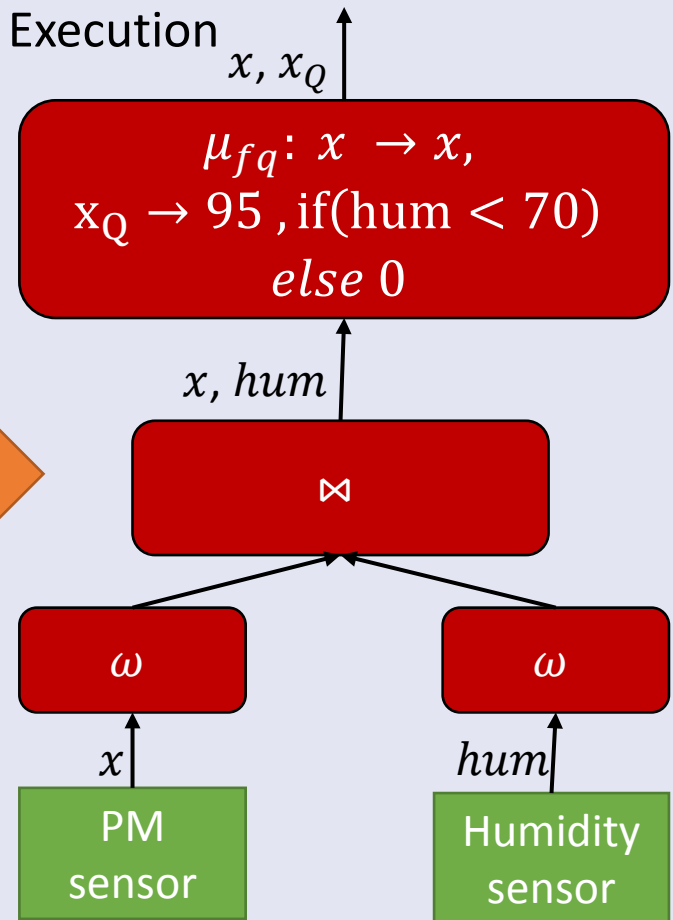
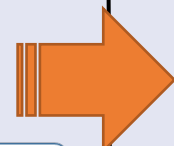
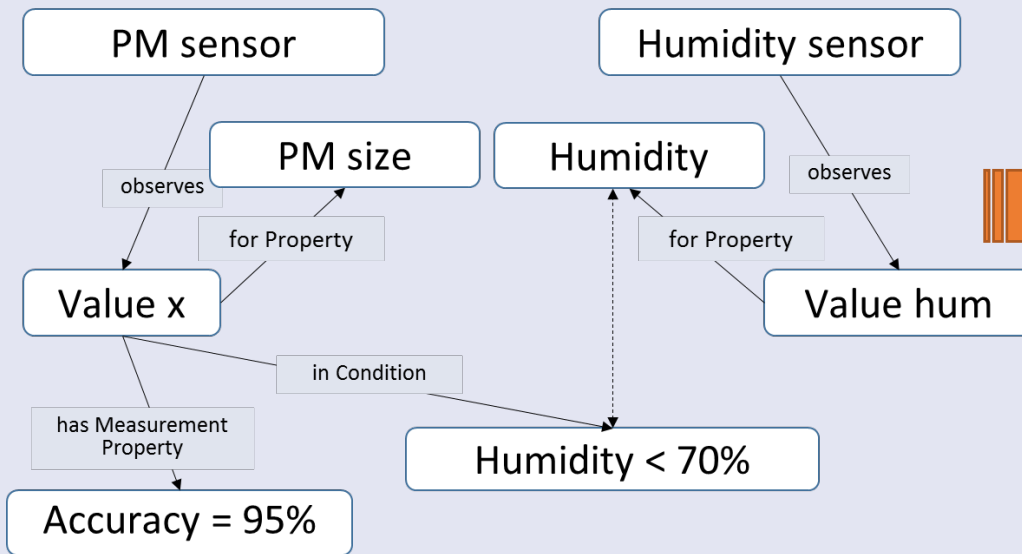


- Mapping linked sensor data to stream processing operators



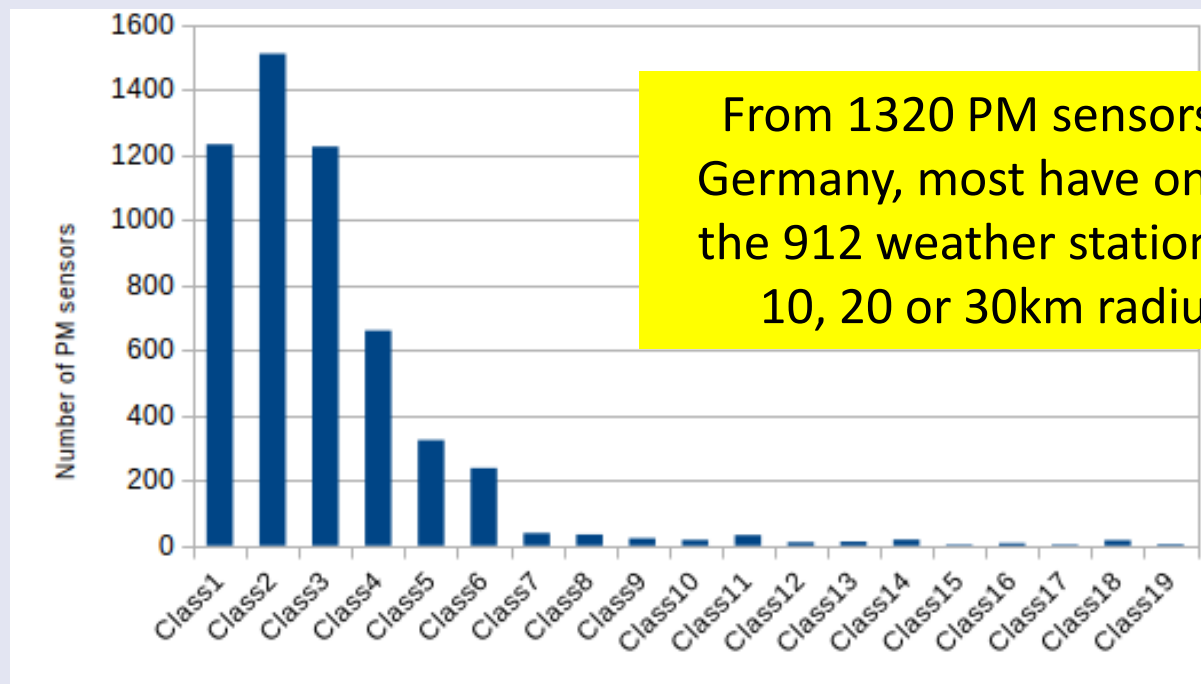
# From ontology to stream processing (3)

Model → Execution



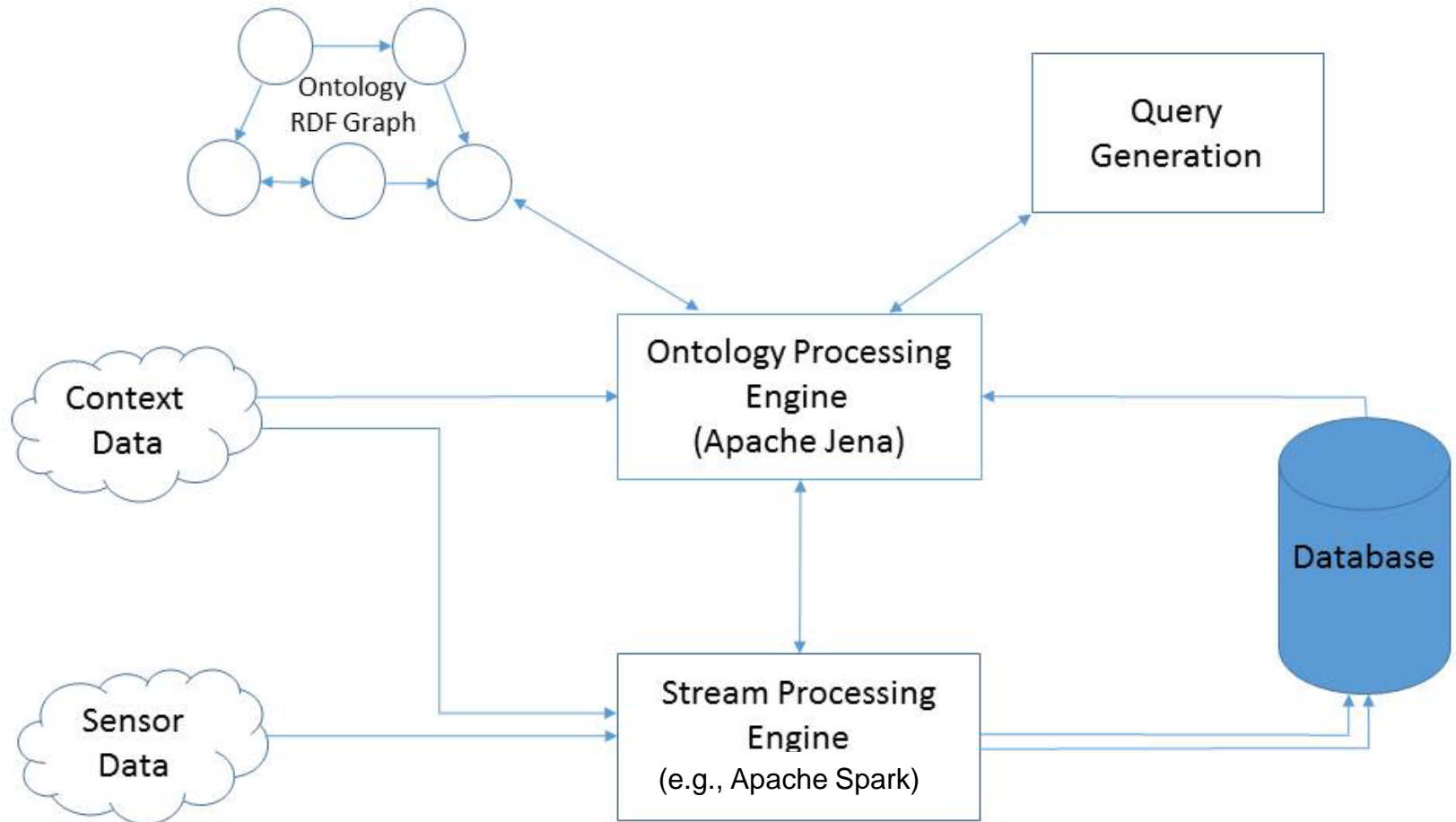
# Which humidity sensors can we use?

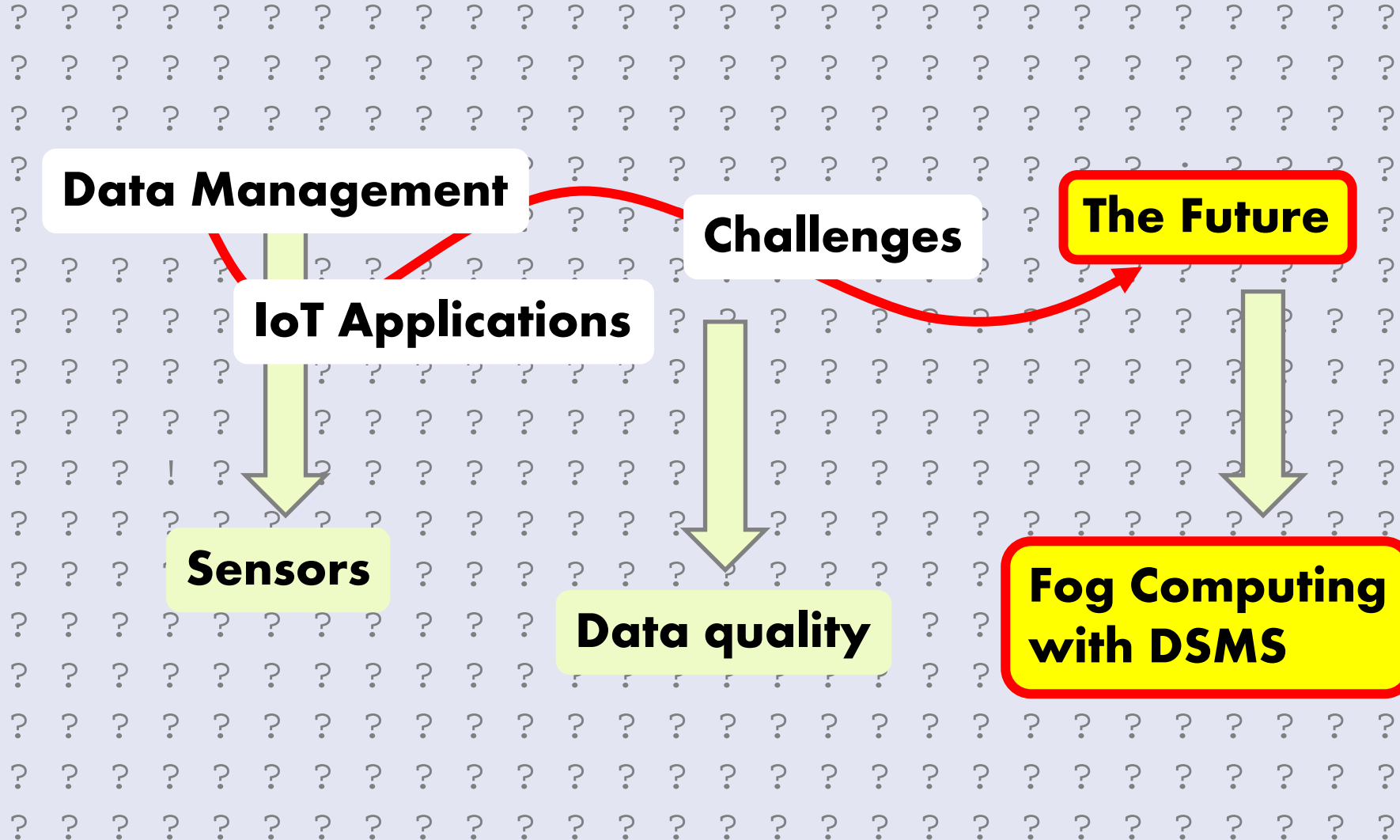
- Can we trust an on-board humidity sensors?
- Or: Use weather stations as data quality reference sources?
- Data from the weather stations used to assess the accuracy of sensors



Number of sensors covered by at least one weather station in 10km radius classes







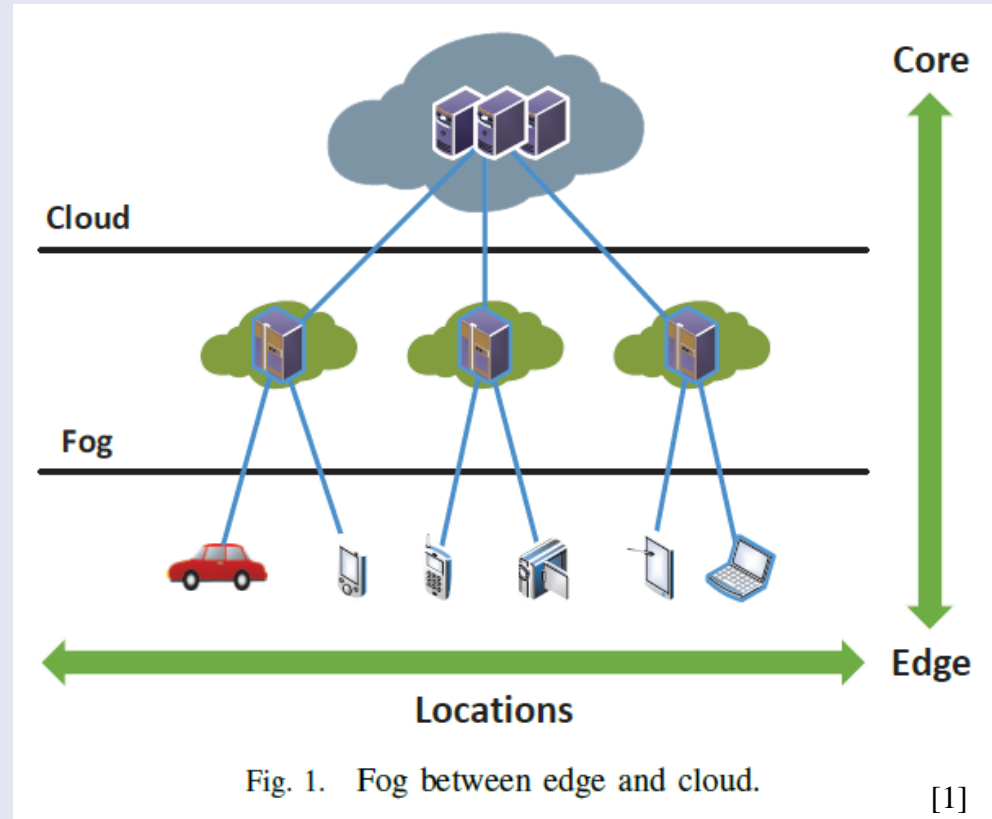
# Perfect data quality for future mobility?



Rush Hour by Fernando Livschitz, Black Sheep films  
<http://vimeo.com/106226560>

# Next step in architectures: Fog Computing

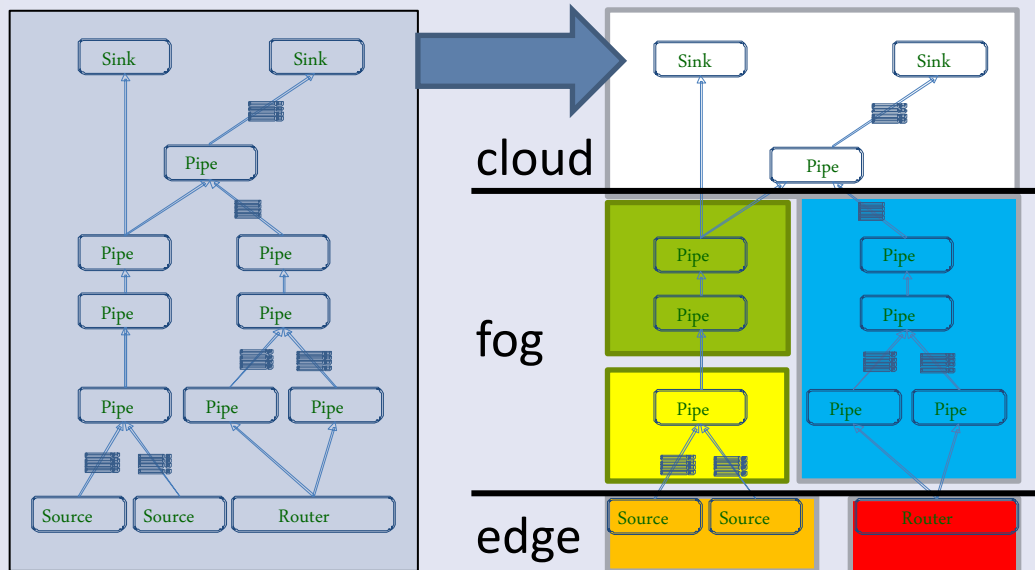
- Sending all raw sensor data to the cloud cannot be the final solution:
  - Bandwidth
  - Energy consumption
    - (computing needs less than communication)
  - Application needs, e.g., privacy
- Edge computing:
  - Move the processing to the edge of the network
- Fog computing:
  - Utilize further processing nodes on the way



[1] I. Stojmenovic and S. Wen, “The Fog Computing Paradigm: Scenarios and Security Issues,” 2014, pp. 1–8.

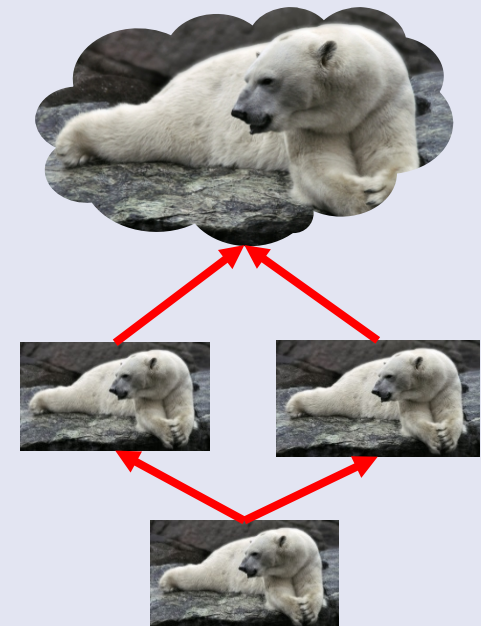
# Fog computing and distributed data stream management

- Data stream management:
  - Provides a higher-level abstraction to stream-based data processing
- Distributed stream management:
  - Distributes the execution of the data stream processing over nodes
  - Finds an optimized query execution plan
  - Can adapt to changing situations and migrate the execution



**We can use distributed DSMS to implement sensor data management in a fog-computing architecture**

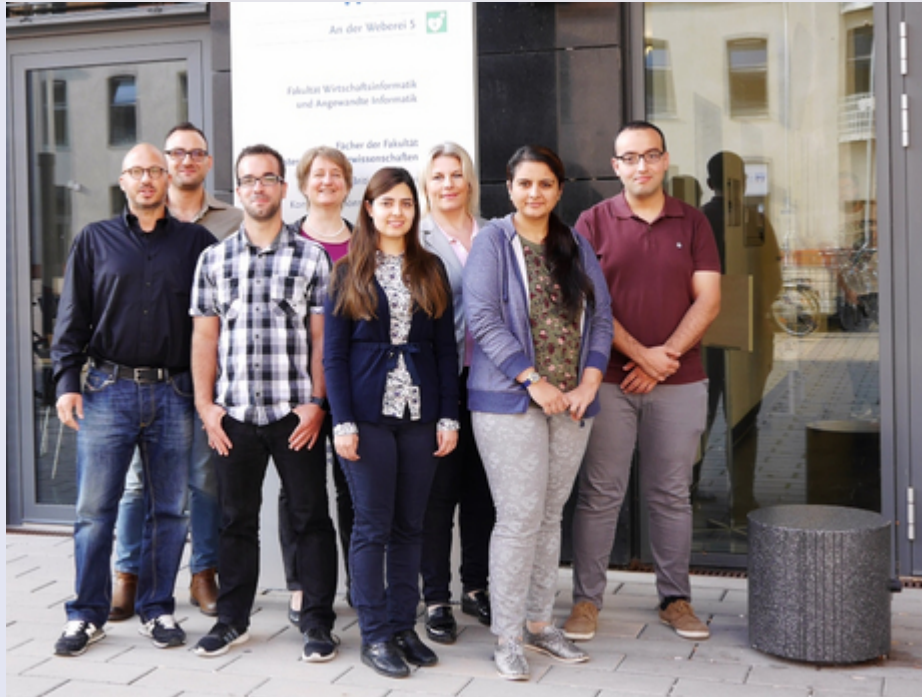
- IoT applications can lead to large-scale sensor data management systems
- Issues to solve:
  - The „V“ challenges → maybe you do not need to store everything in the cloud
  - The „P“ challenge → maybe you can anonymize or aggregate at the edge or in the fog
  - The „Q“ challenge → know thy quality, before and during operation
- IoT platforms can help, but are only slowly moving towards fog architectures („who owns the data?“)
  - Distributed data stream processing revisited?





# Thank's for all the fish!

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Any Questions?

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