

I 
Lustre

FRP + Lustre = Fruste

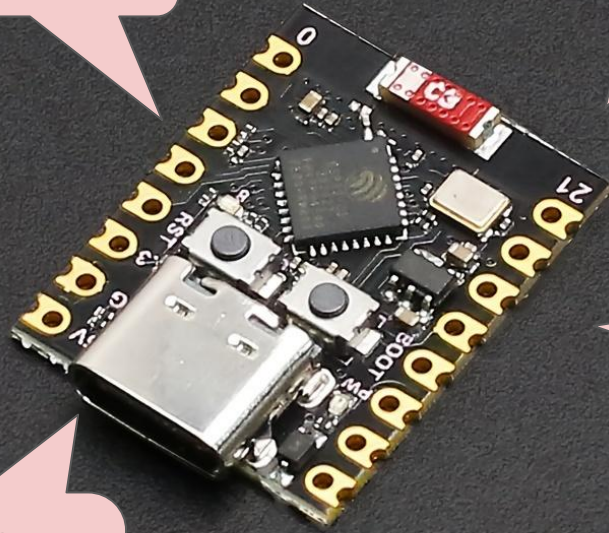
Koen Claessen

little memory

battery
powered

bluetooth/
wifi

timing
sensitive
applications



“Scoria”

MEMOCODE
2022

Creating a Language for Writing Real-Time Applications for the Internet of Things

Robert Krook*, John Hui†, Bo Joel Svensson*, Stephen A. Edwards†, and Koen Claessen*

*Chalmers University of Technology, Gothenburg, Sweden

†Columbia University, New York, USA

Email: krookr@chalmers.se, j-hui@cs.columbia.edu, joels@chalmers.se, sedwards@cs.columbia.edu, and koen@chalmers.se

Abstract—The Scoria language is a real-time language for writing reactive models in a high-level domain-specific language (SSM), designed to generate C code that can be compiled to hardware. Scoria is not yet in a standard form, but we carefully profile the timing behaviour and identify bottlenecks that can improve performance. The language and compiler are implemented as an Embedded Domain-Specific Language (EDSL) on top of Haskell.

Index Terms—Real-time, IoT, Compilers, Embedded Domain-Specific Languages

I. INTRODUCTION

Devices for the Internet of Things (IoT) typically contain hardware for sensors, actuators, and wireless communication, and often need to run on batteries whose life expectancy

imperative
language

Sparse
Synchronous
Model

```
13 else hperiod <- max (deret hperiod 7: 2) 1)
14
15 entry :: (?ble :: BLE, ?out0 :: Ref GPIO) => SSM ()
16 entry = routine $ do
17   hperiod <- var (time2ns (secs 1))
18   fork [sigGen hperiod, remoteControl hperiod]
```

Scoria

```
summer :: Ref Int32 -> Ref Int32 -> SSM ()  
summer diff sum =  
  while true $ do  
    wait diff  
    sum <~ deref sum + deref diff
```

```
ticker :: Int32 -> Ref Int32 -> SSM ()  
ticker n x = routine $ do  
  after (s 1) x n  
  wait x  
  ticker (n+1) x
```

Sparse Synchronous Model

program is in rest
by default

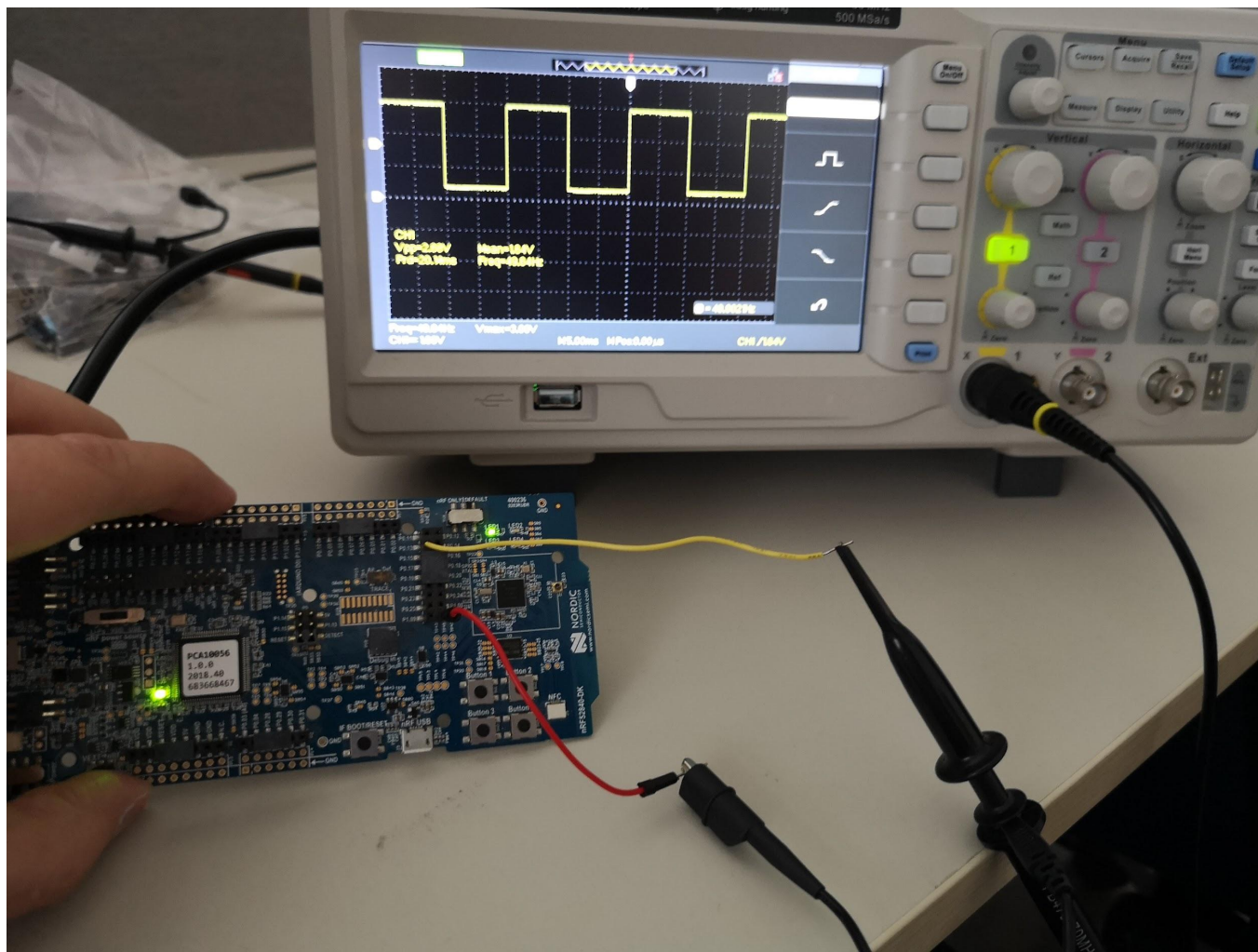
important to limit work
during “reaction”

time does not
pass while
executing code

program reacts to
external triggers

program can
schedule events
in the future

```
1  #include <zephyr.h>
2  #include <drivers/gpio.h>
3
4  /* 1000 msec = 1 sec */
5  #define SLEEP_TIME_MS 50
6
7  static const struct gpio_dt_spec led = GPIO_DT_SPEC_GET(DT_ALIAS(led0), gpios);
8
9  void main(void)
10 {
11     int ret;
12
13     if (!device_is_ready(led.port)) {
14         return;
15     }
16
17     ret = gpio_pin_configure_dt(&led, GPIO_OUTPUT_ACTIVE);
18     if (ret < 0) {
19         return;
20     }
21
22     while (1) {
23         ret = gpio_pin_toggle_dt(&led);
24         if (ret < 0) {
25             return;
26         }
27         k_msleep(SLEEP_TIME_MS);
28     }
29 }
30
```

(Robert Krook)

Trig'd



AUTOSET



I

I

CH1

Vpp=2.68V

Mean=1.68V

Prd=50.16ms

Freq=19.94Hz

f = 19.5694Hz

Freq=19.94Hz

Vmax=3.00V

CH1:: 1.00V

M25.0ms

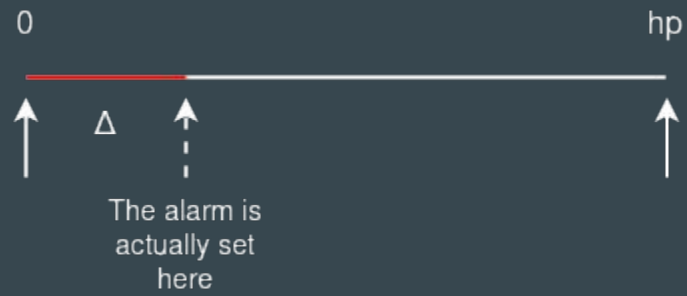
MPos:0.00μs

CH1 /1.64V

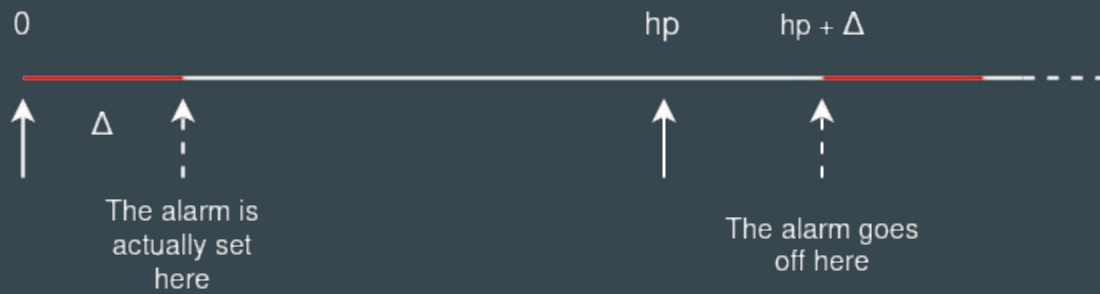
0

hp

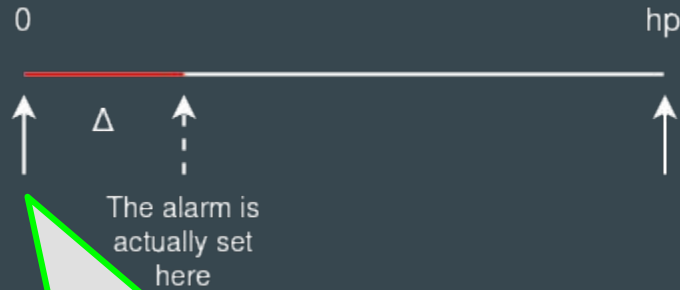








keep track of
logical clock



set alarm from
where you were
supposed to
wake up

Trig'd



AUTOSET



1

1

CH1

Vpp=2.68V

Mean=1.56V

Prd=50.00ms

Freq=20.00Hz

f = 20.5479Hz

Freq=20.00Hz

Vmax=2.92V

CH1 1.00V

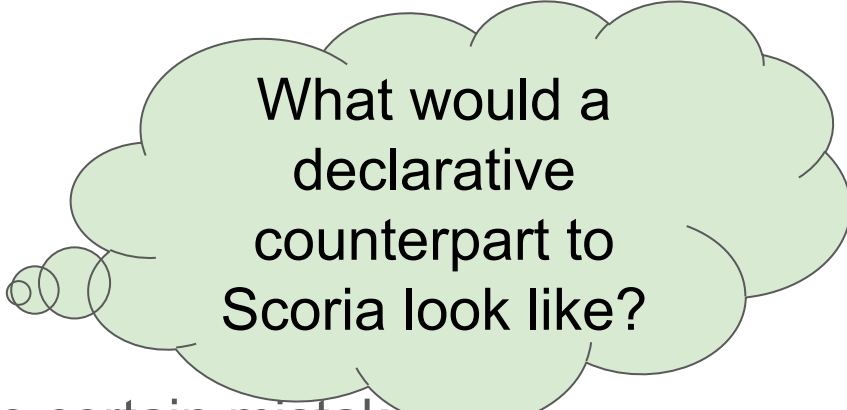
M25.0ms

MPos:0.00μs

CH1 1.56V

Why not Scoria?

- Imperative
 - I like **declarative** languages
 - Declarative = less likely to make certain mistakes (:)
- Process model
 - process dynamically allocated
 - communication between processes is limited (and unintuitive)
 - **run out of time?**
- Memory
 - memory dynamically allocated
 - **run out of memory?**



What would a
declarative
counterpart to
Scoria look like?

Inspiration

Lustre

bounded
memory

bounded
time

declarative

model
checking

never at
rest

no timing
scheduling

FRP

declarative

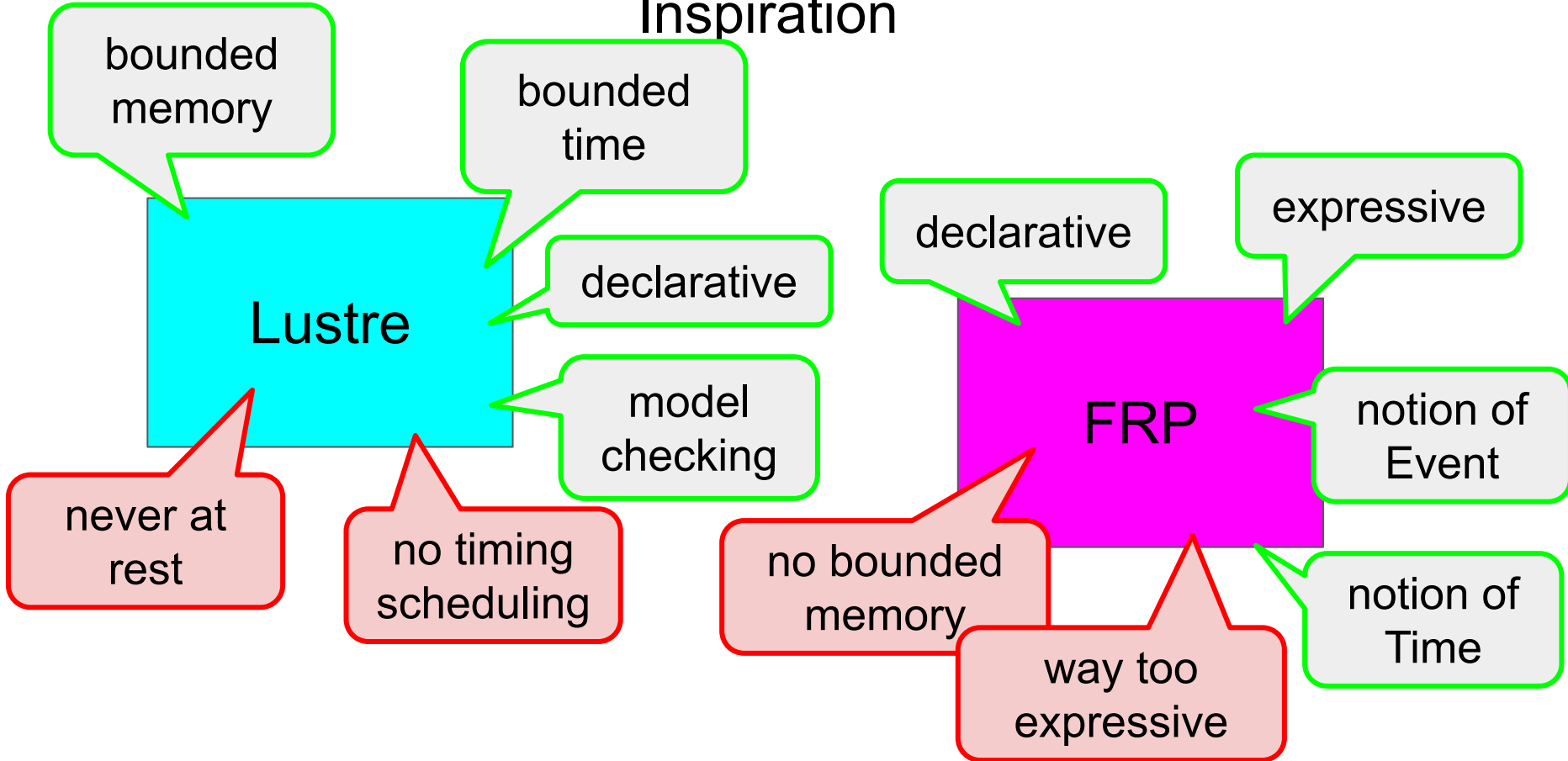
expressive

notion of
Event

notion of
Time

no bounded
memory

way too
expressive



Lustre

constantly
ticking clock

never at
rest

no timing
scheduling

type Signal a ~ [a] {- *infinite* -}

(+) :: Signal Int -> Signal Int -> Signal Int

n :: Signal Int

pre :: Signal a -> Signal a

(→) :: Signal a -> Signal a -> Signal a

pre s = _|_ : s

(x:_) → (_:s) = x:s

summer :: Signal Int -> Signal Int

summer diff = sum

where

sum = diff + (0 → pre sum)

ICFP
1997

Functional Reactive Animation

Conal Elliott
Microsoft Research
Graphics Group
conal@microsoft.com

Paul Hudak
Yale University
Dept. of Computer Science
paul.hudak@yale.edu

Abstract

Fran (Functional Reactive Animation) is a collection of data types and functions for composing richly interactive, multimedia animations. The key ideas in *Fran* are its notions of *behaviors* and *events*. Behaviors are time-varying, reactive values, while events are sets of arbitrarily complex conditions, carrying possibly rich information. Most traditional values can be treated as behaviors, and when images are thus treated, they become animations. Although these notions are captured as data types rather than a programming language, we provide them with a denotational semantics, including a proper treatment of real time, to guide reasoning and implementation. A method to effectively and efficiently perform *event detection* using *interval analysis* is

- capturing and handling sequences of motion input events, even though motion input is conceptually continuous;
- time slicing to update each time-varying animation parameter, even though these parameters conceptually vary in parallel; and

By allowing programmers to express the “what” of an interactive animation, one can hope to then automate the “how” of its presentation. With this point of view, it should not be surprising that a set of richly expressive recursive data types, combined with a declarative programming language, serves comfortably for modeling animations, in contrast with the common practice of using imperative languages to program in the conventional hybrid modeling/-presentation style. Moreover, we have found that non-strict

B = "behavior"

E = "event"

Programming (Fran-style)

Time is
explicit

no bounded
memory / time

type Time ~ Nat

type B a ~ Time -> a -- Monad (Reader)

type E a ~ (Time, a) -- Monad

change :: Eq a => B a -> B (E a)
change b = **do** x <- b; when (/=x) b

switch :: B a -> E (B a) -> B a

(+==>) :: E a -> (Time -> a -> b) -> E b

when :: (a->Bool) -> B a -> B (E a)

summer :: Int -> (Time -> E Int) -> Time -> B Int

summer n diff t =

pure n `switch` (diff t +==> \t' k -> summer (n+k) diff t')



ICFP
2015

Practical Principled FRP

Forget the Past, Change the Future, *FRPNow*!

Atze van der Ploeg Koen Claessen

Chalmers University of Technology, Sweden

{atze,koen}@chalmers.se

Abstract

We present a new interface for practical Functional Reactive Programming (FRP) that (1) is close in spirit to the original FRP ideas, (2) does not have the original space-leak problems, without using arrows or advanced types, and (3) provides a simple and expressive way for performing I/O actions from FRP code. We also provide a denotational semantics for this new interface, and a technique (using Kripke logical relations) for reasoning about which FRP functions may “forget their past”, i.e. which functions do not have an inherent space-leak. Finally, we show how we have implemented this interface as a Haskell library called *FRPNow*.

Categories and Subject Descriptors D.3.2 [Applicative (functional) languages]

Keywords Functional Reactive Programming, Space-leak, Purely

without compromising the original spirit behind FRP, and present an implementation of this interface in Haskell. Our contribution is thus a principled and practical way of programming reactive systems with FRP, without callbacks, nondeterminism or mutable state.

Let us delve a bit deeper into the two problems mentioned earlier.

Space Leaks The first problem, the space leak problem, can be analyzed as follows. A program in FRP can lead to space leaks in three ways:

1. The program using the FRP library can have a space leak.
2. The implementation of the FRP library can have a space leak.
3. The *interface* of the FRP library, i.e. the set of functions offered by the library, can be *inherently leaky*.

Each of these implies the previous: if we have an interface which

Functional Reactive Programming (FRPNow)

type Time ~ *Nat*

type B a ~ *Time* -> a

type E a ~ (*Time*,a)

switch :: B a -> E (B a) -> B a

summer :: Int -> (Time -> E Int) -> Time -> B Int

summer :: Int -> B (E Int) -> B (B Int)

summer n diff =

harder to
write this

Functional Reactive Programming (Fran-s)

```
type Animation = B Image
```

```
text      :: String -> B Image
```

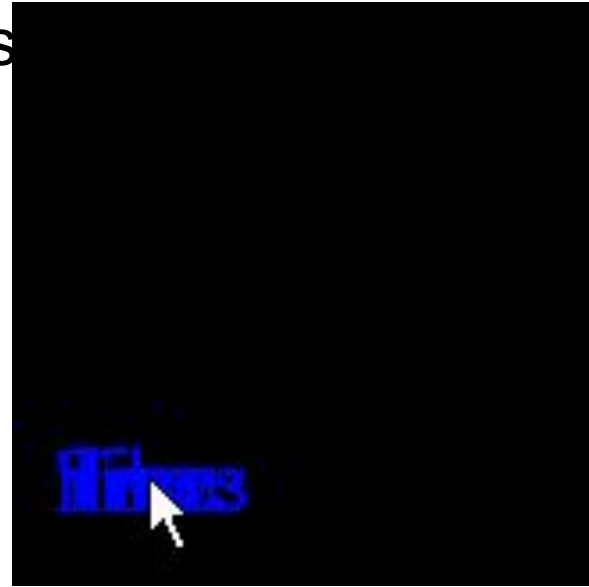
```
over      :: B Image -> B Image -> B Image
```

```
move      :: B (Int,Int) -> B Image -> B Image
```

```
mouseXY   :: B (Int,Int)
```

```
later     :: B Time -> B a -> B a
```

```
foldr1 over $  
  zipWith later [0,1..  
    [ move mouseXY (text w)  
      | w <- words "Time flows like a river" ]
```



Implementing FRP

type E a = *..some kind of blocking mechanism / callback..*

type B a = (a, E (B a))



Small insights

- Lustre has bounded memory because of **pre**
 - no recursion with accumulating parameters
- Let Lustres clock tick only when something happens? - **NO**
 - Haski

Towards Secure IoT Programming in Haskell

Nachiappan Valliappan
Chalmers University of Technology
Gothenburg, Sweden
nacval@chalmers.se

Alejandro Russo
Chalmers University of Technology
Gothenburg, Sweden
russo@chalmers.se

Robert Krook
Chalmers University of Technology
Gothenburg, Sweden
krookr@chalmers.se

Koen Claessen
Chalmers University of Technology
Gothenburg, Sweden
koen@chalmers.se

Abstract

IoT applications are often developed in programming languages with low-level abstractions, where a seemingly innocent mistake might lead to severe security vulnerabilities. Current IoT development tools make it hard to identify these vulnerabilities as they do not provide end-to-end guarantees about how data flows *within and between* appliances. In this work we present Haski, an embedded domain specific language (eDSL) in Haskell for secure programming of IoT devices. Haski enables developers to write Haskell programs that generate C code without falling into many of C's pitfalls. Haski is designed after the synchronous programming language Lustre, and sports a backwards compatible

ACM Reference Format:

Nachiappan Valliappan, Robert Krook, Alejandro Russo, and Koen Claessen. 2020. Towards Secure IoT Programming in Haskell. In *Proceedings of the 13th ACM SIGPLAN International Haskell Symposium (Haskell '20)*, August 27, 2020, Virtual Event, USA. ACM, New York, NY, USA, 15 pages. <https://doi.org/10.1145/3406088.3409027>

1 Introduction

The Internet of Things (IoT) conceives a future where “things” (embedded electronics) can be interconnected. While a compelling vision, recent events have demonstrated the *high vulnerability* of IoT (e.g., [Bertino and Islam 2017; Fernandes

Haski

```
type Temp = Float  
data Status = Home | Away  
data WindowOp = Open | Close | Skip
```

called when
any input
changes

```
halex :: Signal Temp -> Signal Status -> Signal WindowOp
```

Haski

security
labels

keeping track if
halexia does
something “bad”

```
halexia :: Signal Temp -> LSignal Status -> LSignal WindowOp
```

(maybe **Lustre**
clocks are a solution)

Small insights

- Lustre has bounded memory because of **pre**
 - no recursion with accumulating parameters
- Let Lustres clock tick only when something happens? - **NO**
 - Haski
 - Non-modular behavior!

all parts of a
system can
observe when
something
happens

How to schedule
timing events?

Fruste

type Flow a ~ Time -> a

type Stream a ~ [(Time, a)]

zip :: Flow a -> Flow a -> Flow a

n :: Flow Int

(~~>) :: a -> Stream a

pre :: Stream a -> Stream a

sample :: Stream a -> Flow a

merge :: (a->a->a) -> Stream a -> Stream a

```
summer :: Stream Int -> Stream Int
summer diff = sum
```

where

```
sum = diff !+ (0 ~~> pre sum)
```

```
(!+) :: Stream Int -> Flow Int -> Stream Int
s !+ a = fmap (uncurry (+)) (sample s a)
```

```
(><) :: Stream a -> Stream a -> Stream a
s1 >< s2 = merge (\a b ->a) s1 s2
```

```
at :: Flow a -> Stream b -> Stream a
a `at` s = fmap snd (sample s a)
```

generate C
code

at rest

How to
implement

wakes up
at trigger

only run
relevant code
when trigger
happens

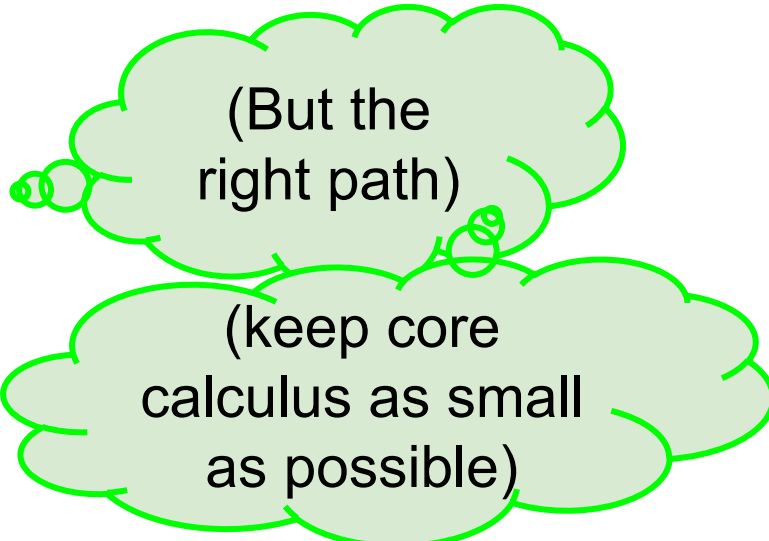
How to
schedule
timing events

Implementing Fruste

type Stream a = *..some kind of blocking mechanism / callback..*

type Flow a = (a, Stream a) *-- created by ~~>*

HARD



(But the
right path)

(keep core
calculus as small
as possible)

Implementing Fruste (easy)

type Flow a = Signal a

reuse Lustre
compiler

type Stream a = (Signal Bool, Signal a)

runs the whole
program every
time something
happens

only has to make
sense when
trigger is True

Fruste implementation

```
(~~>) :: Val a => a -> Stream a -> Flow a  
x ~~> (act, s) = y  
where  
  y = ifThenElse act s (val x --> Lustre.pre y)
```

```
pre :: Stream a -> Stream a  
pre (act, s) = (started' ∧ act, s')  
where  
  started' = false --> Lustre.pre (act ∨ started')  
  s'       =          Lustre.pre (ifThenElse act s s')
```

How to
implement

add small
extension
to Lustre

How to
schedule
timing events

use it to
implement Fruste
timing combinator

Fruste timing

later :: Flow Int -> Stream a -> Stream a

needs
unbounded
memory :-(

later1 :: Flow Int -> Stream a -> Stream a

only schedules 1
event, ignores
everything else

Fruste implementation

Lustre extension

```
timer :: Signal Bool -> Signal Int -> Signal Bool
```

```
later1 :: Flow Int -> Stream a -> Stream a
```

```
later1 t (set,inp) = (get,mem)
```

where

```
get    = timer set t
```

```
ready  = get ∨ (true --> Lustre.pre (nt set ∧ ready))
```

```
mem    = Lustre.pre (ifThenElse (set ∧ ready) inp mem)
```

Fruste examples

```
(>+<) :: Stream Int -> Stream Int -> Stream Int  
s1 >+< s2 = merge (+) s1 s2
```

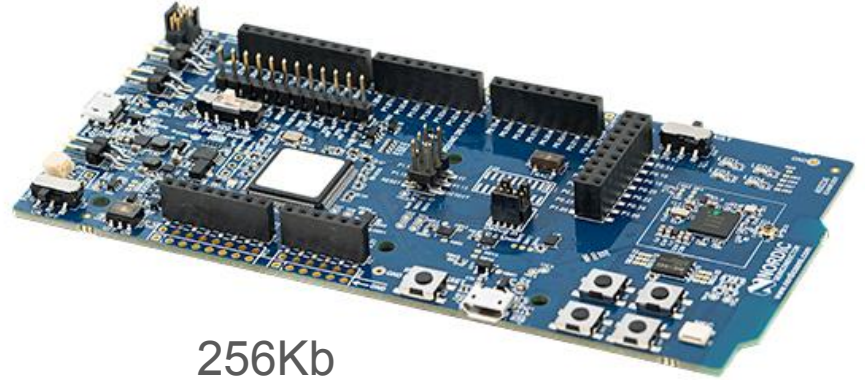
```
ticker :: Flow Int -> Stream ()  
ticker t = s  
  where  
    s = start >< later1 t s
```

DEMO

```
counter :: Stream () -> Stream () -> Stream Int  
counter down up = summer diff  
  where  
    diff = ((-1) `at` down)  
           >+< (1 `at` up)  
           >+< (2 `at` ticking 1000)
```

Nordic Semiconductor NRF52840-DK

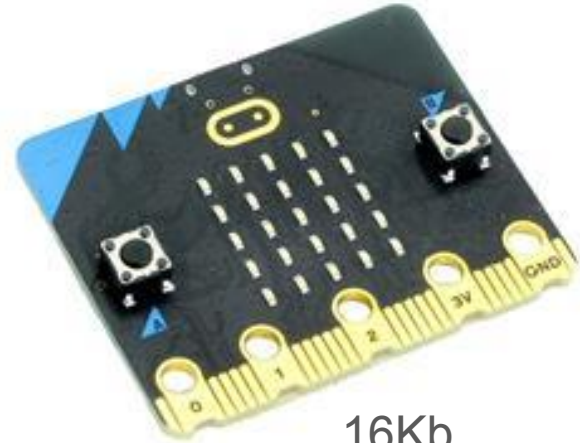
- Development board for IoT-like systems
- Has bluetooth
- Low power
- Fruste runs on Zephyr



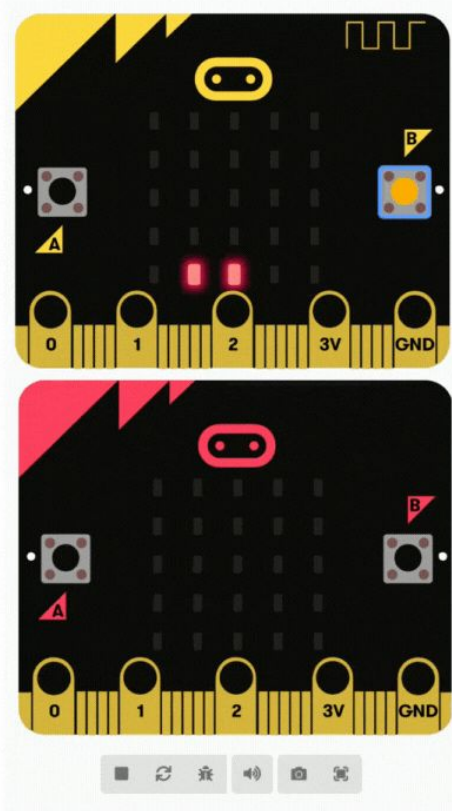
256Kb
Cortex M4 64MHz
BLE

Micro:bit

- Fruste runs on Micro:bit
- Has a 5x5 display
- Has bluetooth
- Low power
- Programming in scratch-like environment
 - or Python
 - or JavaScript
 - (or C)



16Kb
Cortex M0
BLE



```
data System
= System
{ buttonA  :: Stream ()
, buttonB  :: Stream ()
, bltReceive :: Stream Msg
, random   :: Flow Int
...
}
```

bltSend works by
combining all streams
from all parts of the
program

```
arbiter :: System -> (Stream Msg, Stream ())
arbiter sys = (bltSend, victory)
  where
    bltSend = random sys `at` (start >< later1 3 retry)
    sent    = 0 ~~> bltSend

    recv    = bltSend ==> bltReceive sys
    victory = holds (recv !< sent)
    retry   = holds (recv !== sent)
```

$(==>) :: \text{Stream } a \rightarrow \text{Stream } b \rightarrow \text{Stream } b$

only keeps b's
right after a's

```
pingPong :: System -> (Stream Msg, Flow Display)
pingPong sys = (bltSend, display)
where
  (bltSend1, beginMe) = arbiter sys
  (display, endMe)     = gameLogic mbit (beginMe >< endYou)
  (bltSend2, endYou)   = waitLogic endMe

  bltSend = bltSend1 >#< bltSend2
```

merge with
uniqueness **assertion**

“when”

Create something
reactive from
something
non-reactive

```
when :: (a->Bool) -> Flow a -> Stream a
```

OK if all inputs to
the system are
reactive

time :: Flow Time

temp :: Flow Temp

```
when (>30) temp
```

Implementing Flow/Stream



help!

- Only want to execute relevant code in every step
- IDEA 1:
 - Partial evaluation
 - Use same strategy as Lustre clocks
 - (Hard, because Flows always compute, even if their results are not used)
- IDEA 2:
 - Use the “HARD” implementation of Flow/Stream

Future / Ongoing work

- Haski-style security labels
- More serious model checking
 - Predicate abstraction very nice fit with timers
 - “Octogons”
 - Properties
 - Timing is appropriate
 - No double use of shared resources
 - ...